# Positive almost periodic solutions for neural multi-delay logarithmic population model 

Zhouhong Li


#### Abstract

In this paper, by applying Mawhin's continuation theorem of coincidence degree theory, we study the existence of almost periodic solutions for neural multi-delay logarithmic population model and obtain one sufficient condition for the existence of positive almost periodic solution for the above equation. An example is employed to illustrate our result.


Keywords—Almost periodic solution; Multi-delay; Logarithmic population model; Coincidence degree.

## I. Introduction

LU and Ge [1] studied the existence of positive periodic solutions for neutral logarithmic population model with multiple delays. Based on an abstract continuous theorem of $k$-set contractive operator, Luo and Luo [2] investigate the following periodic neutral multi-delay logarithmic population model:

$$
\begin{align*}
\dot{x}(t)= & x(t)\left[r(t)+\sum_{j=1}^{n} a_{j}(t) \ln x\left(t-\sigma_{j}(t)\right)\right. \\
& \left.-\sum_{i=1}^{m} b_{i}(t) \frac{\mathrm{d}}{\mathrm{~d} t} \ln x\left(t-\tau_{i}(t)\right)\right] \tag{1}
\end{align*}
$$

In recently, there has been considerable interest in the existence of periodic solutions of functional differential equations (see, [1-7]). It is well known that the environments of most natural populations change with time and that such changes induce variation in the growth characteristics of populations. Among many population models, the neutral logarithmic population model has recently attracted the attention of many mathematicians and biologists. Since biological and environmental parameters are naturally subject to fluctuation in time, the effects of a periodically varying environment are considered as important selective forces on systems in a fluctuating environment. Therefore, on the one hand, models should take into account the seasonality of the periodically changing environment. However, on the other hand, in fact, it is more realistic to consider almost periodic system than periodic system.

In 2011, J. Alzabuta, et al. consider the positive almost periodic solutions for a delay logarithmicpopulation model, and obtain some sufficient condition on the existence of positive almost periodic solution by applying Mawhin's continuation theorem of coincidence degree theory.

Zhouhong Li is with the Department of Mathematics, Yuxi Normal University, Yuxi, Yunnan 653100, China. E-mail:lzh@yxnu.net

By above, this motivates us to investigate the existence of positive almost periodic solution to system (1), to the best of our knowledge, few results are found in literatures.

The main purpose of this paper is to establish sufficient conditions for the existence of positive almost periodic solutions to system (1) by applying Mawhin's continuation theorem of coincidence degree theory.

The organization of this paper is as follows. In Section 2, we make some preparations. In Section 3, by using Mawhin's continuation theorem of coincidence degree theory, we establish sufficient conditions for the existence of positive almost periodic solutions to system (1). An illustrative example is given in Section 4.

## II. Preliminaries

Our first observation if that under the invariant transformation $x(t)=e^{z(t)}$, equation (1) reduces to

$$
\begin{align*}
\dot{z}(t)= & r(t)-\sum_{j=1}^{n} a_{j}(t) z\left(t-\sigma_{j}(t)\right)-\sum_{i=1}^{m} \\
& \times c_{i}(t) \dot{z}\left(t-\tau_{i}(t)\right) \tag{2}
\end{align*}
$$

where $c_{i}(t)=b_{i}(t)\left(1-\tau_{i}(t)\right), i=1,2, \ldots, m$. We consider equation (2) together with the initial condition

$$
\begin{array}{r}
z(t)=\phi(t), \quad t \in[-\Delta, 0], \quad \Delta=\max _{t \in R^{+}}\left\{\sigma_{j}(t), \tau_{i}(t)\right\} \\
i=1,2, \ldots, n, j=1,2, \ldots, m \tag{3}
\end{array}
$$

For equations (2) and (3), we assume the following conditions:
$(F 1) r(t), a_{j}(t), c_{i}(t) \in C([0,+\infty),[0, \infty))$ are positive functions;
$(F 2) \sigma_{j}(t), \tau_{i}(t) \in C([0,+\infty),[0, \infty))$ are positive bounded functions;
(F3) $\phi(t) \in C([-\Delta, 0],[0, \infty))$.
By a solution of (2) and (3) we mean an absolutely continuous function $z(t)$ defined on $[-\Delta,+\infty)$ satisfying (2) almost everywhere for $t>0$ and (3). As we are interested in solutions of biological significance, we restrict our attention to positive ones.

For the readers' convenience, we first summarize a few concepts from [8].

Let $\mathbf{X}$ and $\mathbf{Z}$ be Banach spaces. Let $L: \operatorname{Dom} L \subset \mathbf{X} \rightarrow \mathbf{Z}$ be a linear mapping and $N: \mathbf{X} \rightarrow \mathbf{Z}$ be a continuous mapping. The mapping $L$ will be called a Fredholm mapping of index zero if $\operatorname{Im} L$ is a closed subspace of $\mathbf{Z}$ and
$\operatorname{dim} \operatorname{Ker} L=\operatorname{codim} \operatorname{Im} L<\infty$.

# International Journal of Engineering, Mathematical and Physical Sciences <br> ISSN: 2517-9934 <br> Vol:6, No:8, 2012 

If $L$ is a Fredholm mapping of index zero, then there exist continuous projectors $P: \mathbf{X} \rightarrow \mathbf{Z}$ and $Q: \mathbf{Z} \rightarrow \mathbf{Z}$ such that $\operatorname{Im} P=\operatorname{Ker} L$ and $\operatorname{Im} L=\operatorname{Ker} Q=\operatorname{Im}(I-Q)$. It follows that

$$
\left.L\right|_{\text {Dom } L \cap \text { Ker } P}:(I-P) \mathbf{X} \rightarrow \operatorname{Im} L
$$

is invertible and its inverse is denoted by $K_{P}$. If $\Omega$ is a bounded open subset of $\mathbf{X}$, the mapping $N$ is called $L$-compact on $\mathbf{X}$, if $Q N(\bar{\Omega})$ is bounded and $K_{P}(I-Q) N: \bar{\Omega} \rightarrow \mathbf{X}$ is compact. Because $\operatorname{Im} Q$ is isomorphic to $\operatorname{Ker} L$, there exists an isomorphism $J: \operatorname{Im} Q \rightarrow \operatorname{Ker} L$.

In the proof of our existence result, we need the following continuation theorem from Gaines and Mawthin [8].
Lemma 1. Let L be a Fredholm mapping of index zero and let $N$ be L-compact on $\mathbf{X}$. Suppose
(1) for each $\lambda \in(0,1), x \in \partial \Omega, L x \neq \lambda N x$;
(2) for each $x \in \partial \Omega, Q N x \neq 0$;
(3) $\operatorname{deg}\{J Q N, \Omega \cap \operatorname{Ker} L, 0\} \neq 0$.

Then $L x=N x$ has at least one solution in $\bar{\Omega} \cap \operatorname{Dom} L$.
Now we introduce some basic notations. Let $A P(\mathbf{R})=$ $\{x(t): x(t)$ is a real valued almost periodic function on $\mathbf{R}\}$. For $f \in A P(\mathbf{R})$ we denote by

$$
\wedge(f)=\left\{\tilde{\lambda} \in R: \lim _{T \rightarrow \infty} \frac{1}{T} \int_{0}^{T} f(s) e^{-i \tilde{\lambda} s} \mathrm{~d} s \neq 0\right\}
$$

and

$$
\begin{aligned}
(\bmod f)= & \left\{\sum_{j=1}^{m} n_{j} \tilde{\lambda}_{j}: n_{j} \in \mathbf{Z}, m \in \mathbf{N}, \tilde{\lambda}_{j} \in \wedge(f)\right. \\
& j=1,2, \ldots, m\}
\end{aligned}
$$

the set of Fourier exponents and the module of $f$, respectively. Let $K(f, \varepsilon, S)$ denote the set of $\epsilon$-almost periods for $f$ with respect to $S \subset \in C([-\Delta, 0],[0, \infty)), l(\epsilon)$ denote the length of the inclusion interval and $m(f)=\frac{1}{T} \int_{0}^{T} f(s) \mathrm{d} s$ denote the mean value of $f$.

Definition 1. $z(t) \in C(\mathbf{R}, \mathbf{R})$ is said to be almost periodic on $\mathbf{R}$ if for any $\varepsilon>0$ the set $K(z, \varepsilon)=\{\delta:\|z(t+\delta)-z(t)\|<$ $\varepsilon, \forall t \in \mathbf{R}\}$ is relatively dense, that is, for any $\varepsilon>0$ it is possible to find a real number $l(\varepsilon)>0$ for any interval with length $l(\varepsilon)>0$, there exists a number $\delta=\delta(\varepsilon)$ in this interval such that $\|z(t+\delta)-z(t)\|<\varepsilon$ for any $t \in \mathbf{R}$.

Throughout of this paper, we assume that the following condition for equation (2)
(F) $r, a_{j}, c_{i} \in A P(\mathbf{R})$ and $m\left[\sum_{j=1}^{n} a_{j}-\sum_{i=1}^{m} c_{i}\right] \neq 0$,
where $m[f]=\lim _{T \rightarrow \infty} \frac{1}{T} \int_{0}^{\infty} f(s) \mathrm{d} s$.
In our case, we shall consider $\mathbf{X}=\mathbf{Z}=V_{1} \bigoplus V_{2}$, where $V_{1}=\{z(t) \in A P(\mathbf{R}): \bmod (x(t)) \subset \bmod (F), \forall \mu \in \Lambda(z(t))$ satisfies $|\mu|>\alpha\}$,

$$
V_{2}=\{x(t) \equiv c \in \mathbf{R}\},
$$

where

$$
F=F(t, \phi)=r(t)-\sum_{j=1}^{n} a_{j}(t) \phi\left(t-\sigma_{j}(t)\right)-\sum_{i=1}^{m} c_{i}(t)
$$

$$
\times \phi^{\prime}\left(t-\tau_{i}(t)\right), \quad \phi \in C([-\Delta, 0], \mathbf{R})
$$

and $\alpha$ is a given positive constant. Define the norm

$$
\|y\|=\sup _{t \in \mathbf{R}}|y(t)| \text { for all } x \in \mathbf{X}(\text { or } \mathbf{Z}) .
$$

We start with the following lemmas.
Lemma 2. X and Z are Banach spaces equipped with the norm $\|\cdot\|$.

Proof: If $\left\{z_{n}\right\} \subset V_{1}$ and $z_{n}$ converges to $y_{0}$, then it is easy to show that $y_{0} \in A P(\mathbf{R})$ with $(\bmod F)$. Indeed, for all $\|\tilde{\lambda}\| \leq \alpha$ we have

$$
\lim _{T \rightarrow \infty} \frac{1}{T} \int_{0}^{\infty} z_{n}(s) e^{-i \tilde{\lambda} s} \mathrm{~d} s=0
$$

Thus

$$
\lim _{T \rightarrow \infty} \frac{1}{T} \int_{0}^{\infty} z_{0}(s) e^{-i \tilde{\lambda} s} \mathrm{~d} s=0
$$

which implies that $z_{0} \in V_{1}$. One can easily see that $V_{1}$ is a Banach space endowed with the norm $\|\cdot\|$. The same can be concluded for the spaces $\mathbf{X}$ and $\mathbf{Z}$. The proof is complete.

Lemma 3. Let $L: \mathbf{X} \rightarrow \mathbf{Z}$ such that $L z=r(t)-$ $\sum_{j=1}^{n} a_{j}(t) z\left(t-\sigma_{j}(t)\right)-\sum_{i=1}^{m} c_{i}(t) z^{\prime}\left(t-\tau_{i}(t)\right)$, where $L z=$ $\frac{\mathrm{d} z}{\mathrm{~d} t}$ Then $L$ is a Fredholm mapping of index zero.

Proof: It is obvious that $L$ is a linear operator and $\operatorname{Ker} L=V_{2}$. It remains to prove that $\operatorname{Im} L=V_{1}$. Suppose that $\phi(t) \in \operatorname{Im} L \subset \mathbf{Z}$. Then, there exists $\phi_{1} \in V_{1}$ and $\phi_{2} \in V_{2}$ such that

$$
\phi=\phi_{1}+\phi_{2} .
$$

From the definitions of $\phi(t)$ and $\phi_{1}(t)$, we can easily see that both $\int^{t} \phi(s) \mathrm{d} s$ and $\int^{t} \phi_{1}(s) \mathrm{d} s$ are almost periodic functions, and so we have $\phi_{2}(t) \equiv 0$ which implies

$$
\operatorname{Im} L \subset V_{1}
$$

On the other hand, if $\varphi(t) \in V_{1} \backslash\{0\}$, then we have $\int_{0}^{t} \varphi(s) \mathrm{d} s \in A P(\mathbf{R})$. By the way, if $\lambda \neq 0$, then we obtain,

$$
\begin{aligned}
& \lim _{T \rightarrow \infty} \frac{1}{T} \int_{0}^{T}\left[\int_{0}^{t} \varphi(s) \mathrm{d} s\right] e^{-i \tilde{\lambda} t} \mathrm{~d} t \\
& \quad=\frac{1}{i \tilde{\lambda}} \lim _{T \rightarrow \infty} \frac{1}{T} \int_{0}^{T} \varphi(t) e^{-i \tilde{\lambda} t} \mathrm{~d} t
\end{aligned}
$$

It follows that

$$
\bigwedge\left[\int_{0}^{t} \varphi(s) \mathrm{d} s-m\left(\int_{0}^{t} \varphi(s) \mathrm{d} s\right)\right]=\bigwedge(\varphi(t))
$$

Thus

$$
\int_{0}^{t} \varphi(s) \mathrm{d} s-m\left(\int_{0}^{t} \varphi(s) \mathrm{d} s\right) \in V_{1} \subset \mathbf{X}
$$

Note that $\int_{0}^{t} \varphi(s) \mathrm{d} s-m\left(\int_{0}^{t} \varphi(s) \mathrm{d} s\right)$ is the primitive of $\varphi(t)$ in $\mathbf{X}$, therefore we have $\varphi(t) \in \operatorname{Im} L$. Hence, we deduce that

$$
V_{1} \subset \operatorname{Im} L
$$

which completes the proof of our claim. Therefore, $\operatorname{Im} L=V_{1}$. Furthermore, one can easily show that $\operatorname{Im} L$ is closed in $\mathbf{Z}$ and

$$
\operatorname{dimKer} L=1=\operatorname{codimIm} L .
$$

Lemma 4. Let $N: \mathbf{X} \rightarrow \mathbf{Z}$,

$$
\begin{aligned}
N z(t)= & r(t)-\sum_{j=1}^{n} a_{j}(t) z\left(t-\sigma_{j}(t)\right) \\
& -\sum_{i=1}^{m} c_{i}(t) z^{\prime}\left(t-\tau_{i}(t)\right) \quad z \in \mathbf{X}
\end{aligned}
$$

and

$$
P: \mathbf{X} \rightarrow \mathbf{X}, P z=m(z) ; Q: \mathbf{Z} \rightarrow \mathbf{Z}, Q z=m(z)
$$

Then $N$ is L-compact on $\bar{\Omega}(\Omega$ is a open bounded subset of $\mathbf{X}$ ).

Proof: Obviously, P and Q are continuous projectors such that,

$$
(\mathrm{I}-\mathrm{Q}) V_{2}=\{0\}, \quad(\mathrm{I}-\mathrm{Q}) V_{1}=V_{1} .
$$

Then, we have

$$
\operatorname{Im}(\mathrm{I}-\mathrm{Q})=V_{1}=\operatorname{Im} L
$$

Now, in view of

$$
\operatorname{Im} P=\operatorname{Ker} L, \operatorname{Im} L=\operatorname{Ker} Q=\operatorname{Im}(I-Q)
$$

we can conclude that the generalized inverse (to $L$ ) $K_{p}$ : $\operatorname{Im} L \rightarrow \operatorname{Ker} P \cap \operatorname{Dom} L$ exists and is given by

$$
K_{p}(z)=\int_{0}^{t} z(s) \mathrm{d} s-m\left[\int_{0}^{t} z(s) \mathrm{d} s\right]
$$

Hence,

$$
\begin{aligned}
Q N z= & m\left[r(t)-\sum_{j=1}^{n} a_{j}(t) z\left(t-\sigma_{j}(t)\right)\right. \\
& \left.-\sum_{i=1}^{m} c_{i}(t) z^{\prime}\left(t-\tau_{i}(t)\right)\right]
\end{aligned}
$$

and

$$
K_{p}(I-Q) N z=f[z(t)]-Q f[z(t)]
$$

where $f[z]$ is defined by

$$
f[z(t)]=\int_{0}^{t}[N z(s)-Q N z(s)]
$$

$Q N$ and $(I-Q) N$ are obviously continuous. Now we are in position to show that $K_{p}$ also is continuous.

By our hypothesis, for any $\varepsilon<1$ and any compact set $s \subset C([-\Delta, 0], R)$, let $l(\varepsilon, S)$ be the inclusion interval of $T(F, \varepsilon, S)$. Suppose $\left\{z_{n}(t)\right\} \subset \operatorname{Im} L=V_{1}$, and $z_{n}(t)$ uniformly converge to $z_{0}(t)$. Because of $\int_{0}^{t} z_{n}(s) \mathrm{d} s \in \mathbf{Z}(n=$ $0,1,2, \ldots)$, there exists $\delta(0<\delta<\varepsilon)$ such that $T(F, \delta, S) \subset$ $T\left(\int_{0}^{t} z_{n}(s) \mathrm{d} s, \varepsilon\right)$. Also, let $l(\delta, S)$ be the inclusion interval of $T(F, \delta, S)$, and

$$
l=\max \{l(\delta, S), l(\varepsilon, S)\}
$$

It is easy to see that $l$ is the inclusion interval of both $T(F, \varepsilon, S)$ and $T(F, \delta, S)$. Hence, for $\forall t \notin[0, l]$, there exists
$\xi_{t} \int(F, \delta, S) \subset T\left(\int_{0}^{t} z_{n}(s) \mathrm{d} s, \varepsilon\right)$ such that $t+\xi_{t} \in[0, l]$. Hence, by the definition of almost periodic function we have

$$
\begin{align*}
& \left\|\int_{0}^{t} z_{n}(s) \mathrm{d} s\right\| \\
= & \sup _{t \in R}\left|\int_{0}^{t} z_{n}(s) \mathrm{d} s\right| \\
\leq & \sup _{t \in[0, l]}\left|\int_{0}^{t} z_{n}(s) \mathrm{d} s\right|+\sup _{t \notin[0, l]} \mid\left(\int_{0}^{t} z_{n}(s) \mathrm{d} s\right. \\
& \left.-\int_{0}^{t+\xi_{t}} z_{n}(s) \mathrm{d} s\right)+\int_{0}^{t+\xi_{t}} z_{n}(s) \mathrm{d} s \mid  \tag{4}\\
\leq & 2 \sup _{t \in[0, l]}\left|\int_{0}^{t} z_{n}(s) \mathrm{d} s\right|+\sup _{t \notin[0, l]} \mid \int_{0}^{t} z_{n}(s) \mathrm{d} s \\
& -\int_{0}^{t+\xi_{t}} z_{n}(s) \mathrm{d} s \mid \\
\leq & 2 \int_{0}^{t}\left|z_{n}(s)\right| \mathrm{d} s+\varepsilon
\end{align*}
$$

by applying (4), we can conclude that $\int_{0}^{t} z(s) \mathrm{d} s(z \in \operatorname{Im} l)$ is continuous, and consequently $K_{p}$ and $K_{p}(I-Q) N z$ also are continuous.

From inequality (4), we also have $\int_{0}^{t} z(s) \mathrm{d} s$ and $K_{p}(I-$ $Q) N z$ are uniformly bounded in $\bar{\Omega}$. In addition, we can easy conclude that $Q N(\bar{\Omega})$ is bounded and $K_{p}(I-Q) N z$ is equicontinuous in $\bar{\Omega}$. By now, by using the Arzela-Ascoli theorem, we can immediately conclude that $K_{p}(I-Q) N \bar{\Omega}$ is compact. Thus $N$ is $L$-compact on $\bar{\Omega}$. The proof of Lemma 2.4 is complete.

Lemma 5. [10] Assume that $x(t) \in A P(\mathbf{R})$, then $x(t)$ is bounded on $\mathbf{R}$.

For the sake of convenience, we introduce notations as follows:

$$
f^{L}=\max _{t \in \mathbf{R}} f(t), \quad f^{l}=\min _{t \in \mathbf{R}} f(t)
$$

where $f$ is a positive continuous almost periodic function.

## III. EXISTENCE OF POSITIVE ALMOST PERIODIC SOLUTION

Theorem 1. Assume that $(F)$ hold, then system (1) has at least one positive almost periodic solution.

Proof: In order to use the continuation theorem of coincidence degree theory to establish the existence of a solution of system (1), we set Banach spaces $\mathbf{X}$ and $\mathbf{Z}$ the same as those in Lemma 2.2 and set mappings $L, N, P, Q$ the same as those in Lemmas 2.3 and 2.4, respectively. Then we can obtain that $L$ is a Fredholm mapping of index zero and $N$ is a continuous operator which is $L$-compact on $\bar{\Omega}$.

Now, we are in the position of searching for an appropriate open, bounded subset $\Omega$ for the application of the continuation theorem. Corresponding to the operator equation

$$
L z=\lambda N z, \quad \lambda \in(0,1)
$$

we obtain

$$
\frac{\mathrm{d} z(t)}{\mathrm{d} t}=\lambda\left[r(t)-\sum_{j=1}^{n} a_{j}(t) z\left(t-\sigma_{j}(t)\right)\right.
$$

$$
\begin{equation*}
\left.-\sum_{i=1}^{m} c_{i}(t) z^{\prime}\left(t-\tau_{i}(t)\right)\right] . \tag{5}
\end{equation*}
$$

Assume that $z \in \mathbf{X}$ is a solution of system (5) for some $\lambda \in(0,1)$. From Lemma 2.5, there must exist $\xi, \eta \in \mathbf{R}$ such that

$$
z(\xi)=\sup _{t \in \mathbf{R}} z(t) \quad \text { and } \quad x(\eta)=\inf _{t \in \mathbf{R}} z(t) .
$$

It is clear that $z^{\prime}(\xi)=0$ and $z^{\prime}(\eta)=0$. From this and system (5), we have

$$
m[r(t)]=m\left[\sum_{j=1}^{n} a_{j}(t) z\left(t-\sigma_{j}(t)\right)\right]
$$

and consequently,

$$
m[r(t)] \geq z(\xi) m\left[\sum_{j=1}^{n} a_{j}(t)\right]
$$

or equivalently

$$
\begin{equation*}
z(\xi) \leq \frac{m[r]}{m\left[\sum_{j=1}^{n} a_{j}\right]} \tag{6}
\end{equation*}
$$

Similarly, we can get

$$
\begin{equation*}
z(\eta) \geq \frac{m[r]}{m\left[\sum_{j=1}^{n} a_{j}\right]} . \tag{7}
\end{equation*}
$$

By the inequalities (6) and (7), we can find that there exists $t_{0} \in \mathbf{R}$ such that

$$
z\left(t_{0}\right) \leq M_{1},
$$

where

$$
M_{1}=\left|\frac{m[r]}{m\left[\sum_{j=1}^{n} a_{j}\right]}\right|+1 .
$$

By virtue of (4), we obtain

$$
\begin{aligned}
\|z(t)\| & \leq\left|z\left(t_{0}\right)\right|+\sup _{t \in \mathbf{R}}\left|\int_{t_{0}}^{t} z^{\prime}(s) d s\right| \\
& \leq M_{1}+2 \sup _{t \in\left[t_{0}, t_{0}+l\right]}\left|\int_{t_{0}}^{t} z^{\prime}(s) \mathrm{d} s\right|+\epsilon
\end{aligned}
$$

or

$$
\begin{equation*}
\|z(t)\| \leq M_{1}+2 \int_{t_{0}}^{t_{0}+l}\left|z^{\prime}(s)\right| \mathrm{d} s+1 \tag{8}
\end{equation*}
$$

Choose a point $\nu-t_{0} \in[l, 2 l] \cap K(F, \rho, S)$, where $\rho(0<\rho<$ $\epsilon)$ satisfies $K(F, \rho) \subset K(y, \epsilon)$. Integrating (5) form $t_{0}$ to $\nu$, we obtain

$$
\begin{align*}
& \lambda \int_{t_{0}}^{\mu}\left[\sum_{j=1}^{n} a_{j}(s)\left(s-\sigma_{j}(s)\right)\right] \mathrm{d} s  \tag{9}\\
= & \lambda \int_{t_{0}}^{\mu}\left[r(s)+\sum_{i=1}^{m} c_{i}(s) z^{\prime}\left(s-\tau_{i}(s)\right)\right] \mathrm{d} s-\int_{t_{0}}^{\mu} z^{\prime}(s) \mathrm{d} s \\
\leq & \lambda \int_{t_{0}}^{\mu}|r(s)| \mathrm{d} s+\epsilon \tag{10}
\end{align*}
$$

However, from (5) and (9), we have

$$
\begin{align*}
& \int_{t_{0}}^{\mu}\left|z^{\prime}(s)\right| \mathrm{d} s \\
\leq & \lambda \int_{t_{0}}^{\mu}|r(s)| \mathrm{d} s+\lambda \int_{t_{0}}^{\mu}\left[\sum_{j=1}^{n} a_{j}(s) z\left(s-\sigma_{j}(s)\right) \mathrm{d} s\right. \\
& \left.+\sum_{i=0}^{m} c_{i}(s) z^{\prime}\left(s-\tau_{i}(s)\right)\right] \mathrm{d} s \\
\leq & 2 \int_{t_{0}}^{\mu}|r(s)| \mathrm{d} s+\epsilon \leq 2 \int_{t_{0}}^{\mu}|r(s)| \mathrm{d} s+1 \tag{11}
\end{align*}
$$

Substituting back in (8) and for $\mu \geq t_{0}+l$, we have

$$
\|z(t)\| \leq M_{2}
$$

where

$$
M_{2}=M_{1}+4 \int_{t_{0}}^{\mu}|r(s)| \mathrm{d} s+3 .
$$

Let $M=M_{2}+\left|\frac{m[r]}{\sum_{j=1}^{n} a_{j}}\right|+1$. Obviously, is is independent of
$\lambda$ Take
入. Take

$$
\Omega=\{z \in \mathbf{X}: z \leq M\}
$$

It is clear that $\Omega$ satisfies assumption (1) of Lemma 2.1. If $y \in \partial \Omega \cap \operatorname{Ker} L$ then $z$ is a constant with $\|z\|=M$. It follows that

$$
\begin{aligned}
& Q N z= m\left[r(t)-\sum_{j=1}^{n} a_{j}(t) z\left(t-\sigma_{j}(t)\right)\right. \\
&\left.-\sum_{i=1}^{n} c_{i}(t) z^{\prime}\left(t-\tau_{i}(t)\right)\right] \\
& \neq 0
\end{aligned}
$$

which implies that assumption (2) of lemma 2.1 is satisfied. Finally, we show that show (3) in Lemma 2.1 holds. The isomorphism $J: \operatorname{Im} Q \rightarrow \operatorname{Ker} L$ is defined by $J(y)=y$ for $y \in \mathbf{R}$. Thus, $J Q N z \neq 0$. In order to compute the Brouwer degree, we consider the homotopy

$$
H(z, s)=-s y+(1-s) J Q N z, \quad 0 \leq s \leq 1
$$

For any $y \in \partial \Omega \cap \operatorname{Ker} L, s \in[0,1]$, we have $H(z, s \neq 0)$. By the homotopic invariance of topological degree, we obtain
$\operatorname{deg}\left\{J Q N, \Omega_{i} \cap \operatorname{Ker} L, 0\right\}=\operatorname{deg}\{-z, \Omega \cap \operatorname{Ker} L, 0\} \neq 0$.
Here, $J$ is taken as the identity mapping. So far we have proved that $\Omega$ satisfy all the conditions in Lemma 2.1. Hence system (2) has at least one almost periodic solution in $\bar{\Omega}$, that is equation (1) has at least one positive almost periodic solution. This completes the proof.

## IV. An example

Now, we give an example to demonstrate our results.
Example 1. Let $r(t)=\cos t, a_{1}(t)=e^{\pi}(2+\cos \sqrt{3} t), c_{1}(t)=$ $e^{\pi}(\sin \sqrt{2} t), \sigma_{1}(t)=\tau_{1}(t)=\frac{\pi}{2}$. Then system (2.1) reduce as flowing

$$
\dot{z}(t)=\sin t-e^{\pi}(2+\cos \sqrt{3} t) z\left(t-\frac{\pi}{2}\right)
$$

$$
\begin{equation*}
-e^{\pi}(\sin \sqrt{2} t) \dot{z}\left(t-\frac{\pi}{2}\right) \tag{12}
\end{equation*}
$$

By calculation, $m\left[a_{1}\right]=e^{\pi} \neq 0$ and thus condition ( F ) holds. Therefore, by the consequence of lemma 2.1, system (12) has at leat one positive almost periodic solution $z(t)$.

## Acknowledgment

The research is supported by the Natural Science Foundation of Yunnan Province, China (Grant No. 2008ZC162M).

## References

[1] S.Lu, W. Ge,Existence of positive periodic solutions for neutral logarithmic pop- ulation model with multiple delays. J. Comput. Appl. Math. 166(2), 371-383 (2004).
[2] Y. Luo, Z. Luo,Existence of positive periodic solutions for neutral multidelay log- arithmic population model. Appl. Math. Comput. 216, 13101315 (2010)
[3] K. Gopalsamy, Stability and Oscillations in Delay Differential Equations of Population Dynamics, Kluwer Acad. Publ., 1992.
[4] M. Kot, Elements of Mathematical Ecology, Cambr. Univ. Press, 2001
[5] Y. Kuang, Delay Differential Equations With Applications in Population Dynamics, Academic Press, Inc., 1993.
[6] J. Alzabuta, G. Stamovb,E. Sermutlu, Positive almost periodic solutions for a delay logarithmicpopulation model.Math. and Comput. Model.,53(12), 161-167(2011).
[7] Q. Wang,H. Zhang, Y. Wang, Existence and stability of positive almost periodic solutions and periodic solutions for a logarithmicpopulation model. Nonlinear Anal: Theory, Methods and Appl.,72(12), 43844389(2010)
[8] Gaines R, Mawhin J. Coincidence degree and nonlinear differentia equations. Berlin: Springer Verlag; 1977.
[9] Y. Xie, X. Li, Almost periodic solutions of single population model with hereditary effects, Appl. Math. Comp. 203,690-697(2008).
[10] C. He, Almost Periodic Differential Equations, Higher Education Pub lishing House, Beijing, 1992 (in Chinese).

