Enhanced GA-Fuzzy OPF under both Normal and Contingent Operation States

Ashish Saini and A.K. Saxena

Abstract—The genetic algorithm (GA) based solution techniques are found suitable for optimization because of their ability of simultaneous multidimensional search. Many GA-variants have been tried in the past to solve optimal power flow (OPF), one of the nonlinear problems of electric power system. The issues like convergence speed and accuracy of the optimal solution obtained after number of generations using GA techniques and handling system constraints in OPF are subjects of discussion. The results obtained for GA-Fuzzy OPF on various power systems have shown faster convergence and lesser generation costs as compared to other approaches. This paper presents an enhanced GA-Fuzzy OPF (EGA-OPF) using penalty factors to handle line flow constraints and load bus voltage limits for both normal network and contingency case with congestion. In addition to crossover and mutation rate adaptation scheme that adapts crossover and mutation probabilities for each generation based on fitness values of previous generations, a block swap operator is also incorporated in proposed EGA-OPF. The line flow limits and load bus voltage magnitude limits are handled by incorporating line overflow and load voltage penalty factors respectively in each chromosome fitness function. The effects of different penalty factors settings are also analyzed under contingent

Keywords—Contingent operation state, Fuzzy rule base, Genetic Algorithms, Optimal Power Flow.

I. INTRODUCTION

ENETIC algorithm [1] (GA) is a general purpose search J theorem which belongs to a class of biologically inspired optimization approaches. Genetic algorithms are used in a wide variety of applications in electric power system. The GA and its variants have been applied to solve unit commitment problem [2], optimal power flow [3-8,19] and for economic load dispatch [9-13]. The objective of OPF is to minimize the fuel cost and keep a secure system in both the normal and contingent states. Conventional calculus-based optimization algorithms have been used in OPF for years. The conventional optimization methods are based on successive linearizations and use the first and second derivatives of objective functions and their constraint equations as the search directions. The conventional optimization methods usually converge to a local minimum.

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The references [9,13] has demonstrated the superiority of GA methods in handling non-differentiable objective and references [2,7] show their ability to handle discrete variables. For better results and faster convergence, conventional GA models have been modified by including new operators such as elitism, shuffle in reproduction, multi-point or uniform crossover and creep mutation.

This paper proposes an application of adaptive EGA-Fuzzy approach with penalty factors to OPF. In EGA-Fuzzy OPF, two important parameters namely, crossover probability (P_c) and mutation probability (P_m) are varied dynamically during the execution of the program according to a fuzzy knowledge base. A new Block Swap Operator (BSO) is included to increase convergence speed and the quality of solutions. The usage of penalty factors to handle line constraints and load bus voltage limits under normal and contingent states of power system are other two significant features of EGA-Fuzzy OPF. Three sets of different penalty factors using EGA-Fuzzy OPF are analyzed for 6 bus system under normal state. The proposed OPF method is also tried for two cases, normal and contingent operation states of IEEE 30 bus system. In the contingent state, the circuit outage of one branch causes a power overflow in the parallel branch and lower voltage limit violations in nearby load buses. The EGA-Fuzzy approach always finds the best results and eliminates operational and insecure violations.

II. OPTIMAL POWER FLOW PROBLEM FORMULATION

The operation of an electric system is complex due to its nonlinear and computational difficulties. One task of operating a power system economically and securely is optimal scheduling, commonly referred to as the optimal power flow problem. The OPF solution gives the optimal active power generation schedule to minimize fuel cost and optimal settings of all-controllable variables e.g. outputs of compensating devices, transformer tap settings and bus voltage levels. Computationally, this is a very demanding nonlinear programming problem due to a large number and type of limit constraints imposed on the power system by engineering design limits.

The objective function of active power dispatch is expressed as follows:

min
$$f_p = \sum_{i \in N_g} (a_i + b_i P_{gi} + c_i P_{gi}^2)$$
 (1)

where a_i , b_i and c_i = cost coefficients of generating unit P_{gi} = real power generation of i^{th} unit N_g = total number of generation units and $i = 1, 2, ..., N_g$

subject to equality and inequality constraints. the equality constraints are:

$$P_{gi} - P_{di} - \sum_{j \in N} |V_i| |V_j| |Y_{ij}| \cos(\delta_i - \delta_j - \theta_{ij}) = 0$$
 (2)

the equality constraints are:

$$P_{gi} - P_{di} - \sum_{j \in N} |V_i| |V_j| |Y_{ij}| \cos(\delta_i - \delta_j - \theta_{ij}) = 0$$

$$Q_{gi} - Q_{di} - \sum_{j \in N} |V_i| |V_j| |Y_{ij}| \sin(\delta_i - \delta_j - \theta_{ij}) = 0$$
(2)

and the inequality constraints are:
$$P_{gi}^{min} \leq P_{gi} \leq P_{gi}^{max} \qquad \qquad i \in N_g \qquad (4)$$

$$Q_{gi}^{min} \leq Q_{gi} \leq Q_{gi}^{max} \qquad \qquad i \in N_g \qquad (5)$$

$$V_{gi}^{min} \leq V_{gi} \leq V_{gi}^{max} \qquad \qquad i \in N_B \qquad (6)$$

$$\delta_{gi}^{min} \leq \delta_{gi} \leq \delta_{gi}^{max} \qquad \qquad i \in N_B \qquad (7)$$

$$Line-MVA_l^{min} \leq Line-MVA_l \leq Line-MVA_l^{max} \qquad i \in n_l \qquad (8)$$

 P_{gi} and Q_{gi} = real and reactive power generation at bus i P_{di} and Q_{di} = real and reactive power demands at bus i

 $|V_i|$ and $|V_i|$ = voltage magnitudes at bus i and j respectively $|Y_{ii}|$ = admittance matrix

 N_B = Total number of buses (Slack, generator and load buses) n_l = total number of lines in system l=1 to n_l

TABLE I MEMBERSHIP FUNCTIONS AND RANGE OF VARIABLES

Variable	Linguistic Terms	Membership Functions
Crossover	Low	\wedge
Probability (P_c)	Medium	
•	High	
	8	
		0.5 0.6 0.7 8 0.95
Mutation	Low	
Probability (P_m)	Medium	
2 ()	High	
	C	
		0.005 0.01 0.02 0.03 0.1
Best	Low	\wedge \wedge \wedge
Fitness (BF)	Medium	
	High	
		0 0.5 0.7 0.9 1
Number of	Low	
generations	Medium	
for unchanged	High	
BF (UN)	· ·	
		0 3 6 9 12
Variance of	Low	\sim \sim
Fitness (VF)	Medium	
	High	
	0**	
		0 0.1 0.12 0.14 0.2

III. ENHANCED GA-FUZZY (EGA-FUZZY) APPROACH FOR **OPF** SOLUTION

After few finite numbers of generations, the fitness value of each chromosome vector becomes almost same (around 0.9). The effect of crossover is insignificant due to very small variation in the chromosome vectors. Therefore, at later stage, increasing the mutation rate of the chromosomes to inculcate new characteristics in the existing population can diversify the population. A GA-Fuzzy approach is used in proposed method in which ranges of GA parameters- crossover probability (P_c) and mutation probability (P_m) have been divided into LOW, MEDIUM and HIGH membership functions and each is given some membership values as shown in Table I.

The GA parameters (P_c and P_m) are varied based on the fitness function values as per following logic:

- i) The value of best fitness for each generation (BF) is expected to change over a number of generations, but if it does not change significantly over a number of generations (UN) then this information is considered to cause changes in both P_c and P_m .
- ii) The diversity of a population is one of the factors, which influences the search for a true optimum. The variance of the fitness values of objective function (VF) of a population is a measure of its diversity. Hence, it is also considered as another factor on which both P_c and P_m may be changed.

The membership functions and membership values for these three variables (BF, UN and VF) are selected after several trials to get optimum results. The GA parameters in proposed algorithm are varied based on fuzzy rules base [19] for the solution of OPF.

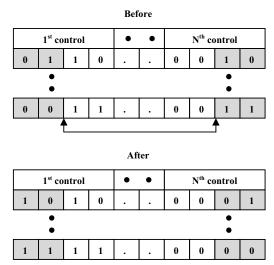


Fig. 1 Application of Block Swap Operator in EGA-Fuzzy OPF

In EGA-Fuzzy OPF, a new block swap operator as shown in fig.1 is applied to introduce random modifications to all chromosomes. It randomly selects out number of columns in a population (blocks) to be swapped. After swapping if the modified chromosome proves to have better fitness, it replaces the original one in the new population. Otherwise, the original chromosome is retained in the new population. It is applied with a probability of 0.3.

Fig.2 is a diagrammatic representation of an approach to incorporate fuzzy logic to find GA based OPF solution. Therefore, approach may be divided broadly in two parts namely EGA-OPF and Fuzzy Rule Base (for controlling the GA parameters P_c and P_m dynamically during execution). EGA-OPF part deals with encoding (of randomly generated chromosomes representing power generation of different generation units, transformer tap settings and shunt capacitor values), running load flow for each set of new generating patterns to determine all line flows, slack bus generation, bus voltages and phase angles, fitness function evaluation and

application of GA operators (Reproduction, Crossover and Mutation) and new block swap operator for each generation.

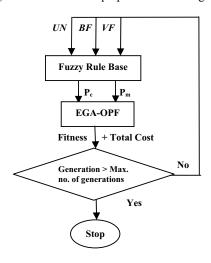


Fig. 2 EGA-Fuzzy approach for OPF problem solving

Load flow using Newton–Raphson method is run for each set of patterns corresponding to active power generations, transformer tap and shunt capacitor settings. It determines slack bus generation, bus voltage magnitudes and phase angles at all the buses. The violations of inequality functional constraints represented by equations (4)-(7) are checked.

GAs are usually designed so to maximize the fitness function (FF), which is a measure of quality of each candidate solution. The objective of the OPF problem is to minimize the total generation cost including power flow constraint for each line i.e. (8) and other equality and inequality constraints stated above. In proposed GA-Fuzzy approach, penalty index (pen_index_i) for each generated chromosome is calculated for lines having power overflows ($over_flow_i$) and load bus voltage magnitude violations ($load\ bus\ voltage\ magnitude\ violation_{lb}$), based on respective penalty factors (p_{ij}) as

$$\sum_{k=1}^{n_l} (p_l \times overflow_l) + \sum_{k=1}^{nload} (p_{lb} \times load \ bus \ voltage \ magnitude \ violation_{lb})$$
 (9)

and fitness function is modified to keep line flows and load bus voltage magnitude under limits as

$$FF_i = \left(\frac{A}{1 + cost_i}\right) \times e^{-(k \times pen_index_i)}$$
 (10)

whereas, i = 1 to population size $n_l = \text{total number of lines in system}$ nload = total number of load buses l = 1 to n_l

lb = 1 to nload

 p_l = penalty factor for overflow in l^{th} line

 $over_flow_l = overflow in l^{th}$ line, if any otherwise zero

 p_{lb} = penalty factor for lb^{th} load bus

load bus voltage violation $_{lb}$ = load bus voltage violation in lb^{lh} load bus, if any otherwise zero

pen $index_i$ = penalty index for i^{th} chromosome

A and k = large numerical constant $cost_i =$ generation cost corresponding to i^{th} chromosome $FF_i =$ fitness value of function for i^{th} chromosome.

IV. EXPERIMENTS AND RESULTS

The proposed GA-Fuzzy algorithm for solution of the OPF has been implemented on 6 bus [14] and IEEE 30 bus system [17]. The test examples have been run on 1.7 GHz Celeron with 128 MB RAM PC.

A. For 6 bus

Table II depict the values of EGA-Fuzzy parameters used for the test system.

TABLE II EGA-FUZZY PARAMETERS FOR 6 BUS SYSTEM

Crossover probability	Mutation probability	Selection operator	Population size	Maximum number of generations
0.9 (Initial)	0.01 (Initial)	Stochastic Remainder	50	200

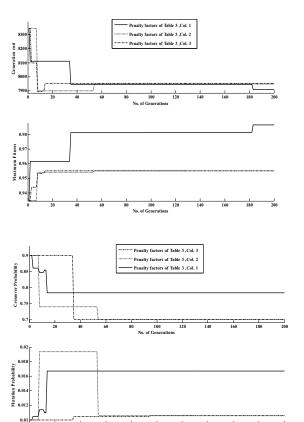


Fig. 3 Convergence of generation cost, maximum fitness, crossover and mutation probabilities for different penalty factors settings for 6 bus system using EGA-Fuzzy OPF

 $TABLE\,III$ Lineflows, load bus voltages, overflow line and load voltage penalty factors, loadflow solutions and generation costs for different overflow line penalty factors settings using EGA-Fuzzy OPF for 6 bus system

			EGA-Fuzzy OPF			E	GA-Fuzz	y OPF	EGA-Fuzzy OPF		
From bus	To bus	Line flows		Column-1			Colum	n-2	Column-3		
no.	no.	limits	Over	flow line	Line flow	s Overf	low line	Line flows	Overflow line	Line flows	
		(MVA)	penal	ty factors	(MVA)	penalt	y factors	(MVA)	penalty factors	(MVA)	
1	2	100		1	30.936		1	33.744	1	33.547	
1	5	100		1	74.224		1	63.610	1	63.826	
2	4	100		1	56.719		1	57.428	1	57.629	
3	5	100		1	53.317		1	40.396	1	40.428	
3	6	100		1	31.562		1	35.631	1	35.659	
4	5	50		1	49.136		20	41.698	25	41.556	
4	6	100		5	87.922		10	74.194	10	74.138	
		Load B	us volta	ge (in p.u.)			V. max		min T /		
							V load =	= 1.06 p.u.	$V_{load} = 0.94 p.$	u.	
	EGA Fuzzy OPF						EGA Fuzzy OPF			EGA Fuzzy OPF	
Load bus			Column	-1	Column-2			Column-3			
		Load voltage	Bus voltage (in		(in Loa	Load voltage Bus voltage			Load voltage	Bus voltage	
		penalty factor	s p.	u.)	pen	penalty factors (in p.u.)			penalty factors	(in p.u.)	
5		1	0.	977			0.977		1	0.977	
6		1	0.	981			0.981		1	0.981	
		Active	Power g	eneration			$P_g^{max} = 2$		min 50 N SIV		
							rg ≡ ∠ max	00 111 11	g = 50 MW		
		Gener	ator bus	voltage			17	17	g = 0.94 p.u.		
		Bus	l	F	Bus 2	1100 Pian			Bus 4	Generation	
			olt. (in		Volt. (in	Gen.	Volt. (ii		Volt. (in	Cost	
			.u.)	(in p.u.)	p.u.)	(in p.u.)	p.u.)	(in p.u.)	p.u.)	(in \$/hr)	
EGA Fus	ZZV OPE	(III p.u.) p)	(p.u.)	r.u.)	(III p.u.)	P.u.,	(III p.u.)	p.u.,	(4,)	
EGA Fuzzy OPF Column-1		1.43729 1	.001	1.86852	1.017	0.98680	1.010	1.80205	1.000	7910.2065	
EGA Fuz		1.73/2) 1	.001	1.00052	1.01/	3.70000	1.010	1.00203	1.000	, , 10.2003	
Colu	-	1.30182 1	.001	1.90762	1.017	1.27810	1.010	1.58700	1.000	7948.6284	
EGA Fuz		1.50102 1	.001	1.70/02	1.01/	1.2/010	1.010	1.56700	1.000	7740.0204	
Colu	•	1.30582 1	.001	1.90762	1.017	1.27810	1.010	1.58309	1.000	7954.6801	

TABLE IV Line flows for penalty factors settings (Table 3, Column 2 and Column 3) during 10^{th} generation for 6-bus system

From bus no.	To bus no.	For penalty factors in Table III Column 2	For penalty factors in Table III Column 3
		during 10 th generation	during 10 th generation
1	2	29.77	33.076
1	5	83.822	85.357
2	4	58.131	62.424
3	5	65.958	68.788
3	6	27.537	28.507
4	5	59.259 (overflow)	60.673 (overflow)
4	6	101.883 (overflow)	104.229 (overflow)
Generat	ion Cost	7900.4	7897.0
Max.	fitness	0.9542	0.9532

 $\label{table v} TABLE\ V$ Comparison of generation cost with other methods for 6-bus system

OPF method	Weber [14]	OPFSA [15]	M-COGA [16]	EGA-Fuzzy OPF Column-1
Generation Cost (\$/h)	8062	7938	7987.1764	7910.2065

Three cases using different overflow line penalty factors settings named as EGA-Fuzzy OPF Column-1, EGA-Fuzzy OPF Column-2 and EGA-Fuzzy OPF Column-3 (as listed in Table III) are tried under normal state.

The load voltage penalty factors are kept same because lower limits of load bus voltage magnitudes are not violated in normal state operation. The convergence curves for generation cost and maximum fitness and variations in crossover and mutation probabilities are shown in fig. 3. The lineflows, load bus voltages, penalty factor settings, loadflow solutions and generation costs for three cases are tabulated in Table III. For EGA-Fuzzy OPF Column-1, generation cost is lowest and maximum fitness has maximum value among all the cases, though line flow is just under control at line 4-5. If higher values of penalty factors (EGA-Fuzzy OPF Column-2 and Column-3 of Table III) are chosen overcautiously, then line flows will be under control but with suboptimal generation costs.

Another major observation made in fig. 3 is that lower generation costs with lower maximum fitness values are obtained from generation number 10th to 56th generation (for EGA-Fuzzy OPF Coloumn-2 penalty factors) and from 10th to 17th generation (for EGA-Fuzzy OPF Coloumn-3 penalty factors). The results tabulated in Table IV indicate that during 10th generation overflows are resulted at lines 4-5 and 4-6 with lower generation costs and lower maximum fitness values. Although comparatively higher generation costs and higher maximum fitness values with no line overflows are obtained during later stages/generations of optimization. The reason being that during earlier generations, fitness function defined by (10) with exponentially decaying terms for line overflows and lower load bus voltage limits, gives lower maximum fitness values due to line overflows resulted by generation schedule.

The proposed EGA-Fuzzy OPF method has minimum generation cost with no line overflows and load voltage magnitude limits violation among other OPF methods listed in Table V.

B. For IEEE 30-bus

The IEEE 30-bus system consists of six generators, four transformers, 41 lines and nine shunt capacitors. The variable limits and generator cost parameters are listed in Table VI.

Two cases are studied. Case-1 is the normal operation case and the Case-2 is the contingent case, in which a circuit outage is simulated in branch (6,28) thus causing a power flow violation in branch (8,28) and violation of some load bus voltage magnitude limits. The GA parameters of EGA-Fuzzy OPF and optimal results for Case-1 are given in Table VII and Table VIII respectively. All power and voltage quantities are in per unit values. The base power is 100 MVA.

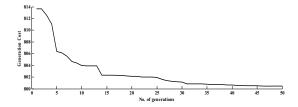
The convergence to final values of generation cost and maximum fitness along with crossover and mutation probabilities variations for Case-1 using EGA-OPF are shown in fig. 4.

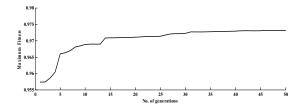
TABLE VI VARIABLE LIMITS AND GENERATOR COST PARAMETERS OF IEEE 30-BUS SYSTEM

Power generation limits and fuel cost parameters ($S_B = 100 \text{ MVA}$)								
Bus	1	2	5	8	11	13		
Pg max	2	0.8	0.5	0.35	0.3	0.4		
$P_{\rm g}^{ { m min}}$	0.5	0.2	0.15	0.1	0.1	0.12		
Q_g^{max}	2	1	0.8	0.6	0.5	0.6		
Q_g^{min}	- 0.2	- 0.2	- 0.15	- 0.15	- 0.1	-0.15		
a	0	0	0	0	0	0		
b	200	175	100	325	300	300		
c	37.5	175	625	83.4	250	250		
Bu	s voltage	e limits (in	p.u.)	Branc	h apparer	nt power		
V_{g}^{max}	$V_{\rm g}^{\rm min}$	V_{load}^{max}	${ m V}_{ m load}^{ m min}$	limit S k (in MVA) Branch (8, 28)				
1.1	0.95	1.05	0.95	. 12				

TABLE VII EGA-FUZZY PARAMETERS FOR IEEE 30 BUS

Crossover probability	Mutation probability	Selection operator	Population size
0.95 (Initial)	0.01 (Initial)	Stochastic Remainder	50





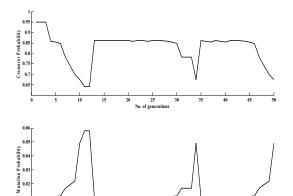


Fig. 4 Convergence of generation cost, maximum fitness, crossover and mutation probabilities using EGA-Fuzzy OPF for Case-1 of IEEE 30-bus

 $TABLE\ VIII$ Lineflows, load bus voltages, overflow line and load voltage penalty factors, loadflow solution, and generation cost for Case-1 (Normal State) of IEEE 30 bus using EGA-Fuzzy OPF

From	To bus no.	Line flows	EGA-Fu	zzy OPF	At load	EGA-Fuzzy OPF			
bus no.		limits (MVA	Overflow line penalty factors	Line flows (MVA)	bus -	Load volta penalty fact	_	oltage (in p.u.	
1	2	130	1	117.0092	3	1	1.05		
1	3	130	1	58.3399	4	1	1.043		
2	4	65	1	33.8512	6	1	1.038		
2	5	130	1	63.6081	7	1	1.027		
2	6	65	1	44.859	9	1	1.062		
3	4	130	1	54.2265	10	1	1.054		
4	6	90	1	48.829	12	1	1.057		
4	12	65	1	30.6851	14	1	1.047		
5	7	70	1	14.1992	15	1	1.047		
6	7	130	1	34.697	16	1	1.05		
6	8	32	1	11.1877	17	1	1.05		
6	9	65	1	19.9662	18	1	1.04		
6	10	32	1	13.188	19	1	1.04		
6	28	32	1	16.2027	20	1	1.045		
8	28	12	1	3.3171	21	1	1.045		
9	11	65	1	20.8172	22	1	1.045		
9	10	65	1	32.64054	23	1	1.045		
10	20	32	1	9.4703	24	1	1.043		
10	17	32	1	6.3406	25	1	1.039		
10	21	32	1	16.5742	26	1	1.045		
10	22	32	1			1			
12			1	7.8564	27 28		1.054		
12	13	65 32	1	15.6675	28 29	1	1.034		
12	14 15	32	1	7.4018	30	1 1	1.041		
			1	17.485	30	1	1.027		
12 14	16 15	32 16	1	6.6516					
			1	1.6794					
15	18	16	1	5.5863					
15	23	16	1	4.8064					
16	17 19	16		3.3993					
18		16	1	2.3973					
19	20	32	1	8.1734					
21	22	32	1	2.6539					
22	24	16	1	5.7204					
23	24	16	1	2.1442					
24	25	16	1	1.6587					
25	26	16	1	4.2584					
25	27	16	1	5.8553					
27	29	16	1	6.1908					
27	30	16	1	7.145					
28	27	65	1	19.1927					
29	30	16	1	3.8992					
		er tap settings							
Branch	(6,9)		(6,10)		(4,12)		(28,27)		
	0.9903 Shunt car	pacitor (in p.u.)	0.9839		0.9903		0.9645		
Bus	10		5 17	20	21	23	24	29	
Dus	0.03982		.04149 0.0499		0.04354	0.0454	0.04687	0.02097	
			rations (in p.u.)	0.04432	0.04334	0.0424	0.0700/	0.0207/	
Bus	1	ve power gener 2	5	8	11	13			
Gen. (in			8941 0.21176	0.22647	0.12588		Generation Cos	st (in \$/hr)	
con. (III		.081 1.0		1.039	1.095		800.442	π (111 ψ/111)	

As the results listed in Table VIII for Case-1, with unity penalty factors settings for line flow constraints and load bus voltage magnitude, all generator units are scheduled for minimum generation cost 800.442\$/hr without any operational and insecure violations.

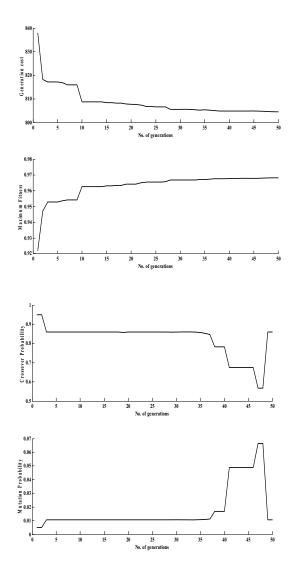


Fig. 4 Convergence of generation cost, maximum fitness, crossover and mutation probabilities for EGA-Fuzzy OPF for Case-2, Solution-1 of IEEE 30-bus

For same system settings but circuit outage of branch (6,28), power flow in branch (8,28) exceeds the maximum limit along with voltage magnitude drop at load buses 25, 26, 27, 29 and 30. In Case-2 (contingent state with congestion state), Solution-1 and Solution-2 are obtained using EGA-Fuzzy OPF with same penalty factors for line flows but different penalty factors for load bus voltage magnitude. Fig. 4 and 5 show convergence and variations in crossover and mutation probabilities for Case-2, Solution-1 and Case-2, Solution-2 respectively.

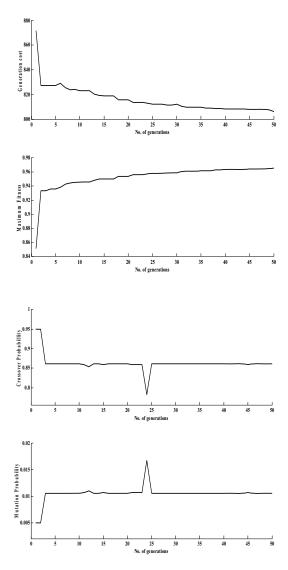


Fig. 5 Convergence of generation cost, maximum fitness, crossover and mutation probabilities using EGA-Fuzzy OPF for Case-2, Solution-2 of IEEE 30-bus

It is clear from results listed in Table IX, the line flows and load bus voltage magnitudes are under limits for penalty factors values used in Case-2, Solution-1. The line flows are well under control but with scanty violation of load bus voltage magnitude at bus 30 (\approx 0.945) in Case-2, Solution-2 due to selecting unity penalty factor settings for load buses.

Table X shows the comparison of the cost of generation for IEEE 30-bus system for both the cases with other available methods and shows it's superiority over others.

TABLE IX

LINEFLOWS, LOAD BUS VOLTAGES, OVERFLOW FLOW LINE AND LOAD VOLTAGE PENALTY FACTORS, LOADFLOW SOLUTION, AND GENERATION COST FOR

From	То	Line	EGA-Fu	CONTINGENCY IZZY OPF	EGA-	Fuzzy OPF	At	EGA-	Fuzzy OPF		uzzy OPF
bus	bus	flows		tion-1		ution-2	_ load		lution-1		ıtion-2
no.	no.	limits (MVA)	Overflow	Line flows (MVA)	Overflow line	Line flow (MVA)	s bus			Load	Bus voltage
		(MVA)	line penalty factors	(IVI V A)	penalty	(MVA)		voltag penalt		voltage penalty	(in p.u.)
			iactors		factors			factor		factors	(m p.u.
1	2	130	1	117.0941	1	122.3225	3	5	1.058	1	1.029
1	3	130	1	58.0893	1	58.7672	4	5	1.051	1	1.022
2	4	65	1	35.2645	1	35.5066	6	5	1.046	1	1.016
2	5	130	1	65.2592	1	64.8939	7	5	1.048	1	1.000
2	6	65	1	45.8348	1	46.1278	9	5	1.098	1	1.089
3	4	130	1	53.9314	1	54.578	10	5	1.088	1	1.066
4	6	90	1	47.2856	1	47.441	12	5	1.09	1	1.078
4	12	65	1	32.7012	1	32.9166	14	5	1.078	1	1.063
5	7	70	1	27.0514	1	11.7813	15	5	1.075	1	1.057
6	7	130	1	35.194	1	35.7528	16	5	1.084	1	1.067
6	8	32	1	29.7604	1	32.0634	17	5	1.083	1	1.064
6	9	65	1		1						
				30.9893		26.2947	18	5	1.07	1	1.051
6	10	32	1	22.0905	1	13.8451	19	5	1.07	1	1.05
8	28	12	50	11.7912	50	11.9848	20	5	1.075	1	1.055
9	11	65	1	16.6787	1	17.1137	21	5	1.074	1	1.051
9	10	65	1	35.587	1	41.9316	22	5	1.073	1	1.05
10	20	32	1	9.8212	1	9.4945	23	5	1.058	1	1.041
10	17	32	1	6.9061	1	5.5112	24	5	1.045	1	1.024
10	21	32	1	22.56	1	23.014	25	5	1.001	1	0.987
10	22	32	1	11.6946	1	11.775	26	5	0.983	1	0.969
12	13	65	1	15.0569	1	21.6305	27	5	0.983	1	0.974
12	14	32	1	8.1769	1	8.5667	28	5	1.051	1	1.022
12	15	32	1	19.5271	1	20.5364	29	5	0.962	1	0.96
12	16	32	1	7.132	1	7.5278	30	5	0.95	1	0.945
14	15	16	1	1.7774	1	2.0485					
15	18	16	1	5.559	1	5.6891					
15	23	16	1	8.7343	1	8.694					
16	17	16	1	3.8799	1	3.6635					
18	19	16	1	2.679	1	2.534					
19	20	32	1	8.6167	1	8.137					
21	22	32	1	4.0246	1	2.6012					
22	24	16	1	14.9637	1	13.952					
23	24	16	1	5.1721	1	6.1589					
24	25	16	1	12.0123	1	9.8722					
2 4 25	26	16	1	4.2647	1	4.2669					
25 25	27	16	1	7.9349	1	5.7534					
23 27	29	16									
			1	6.4275	1	6.2131					
27	30	16	1	7.3044	1	7.1688					
28	27	65	1	11.7875	1	11.9811					
29	30	16	1	3.7575	1	3.9264					
	_		Transformer			(6.40)					
	Branc	ch		(6,9)		(6,10)		(4	1,12)	(2	28,27)
\$	Solutio	on-1		0.9194		0.9		0.	9581	1	.0871
	Solutio	on-2		0.9065		0.9452		0.	9452	1	.0678
			Shunt capac								
Bu		10	12	15	17	20		21	23	24	29
Solut	ion-1	0.04824	0.0382			0.0312	1 0.0	03268	0.0009	0.04002	0.00000
Solut	ion-2	0.02681	0.01429	9 0.0057	7 0.0428	36 0.0330	7 0.0	00685	0.01526	0.01517	0.02258
		Bus	1	2 5		11		13	Genera	tion Cost (in \$/hr)
Solutio	n-1	Gen. (in p.u	.) 1.73494	0.52471 0	.21589 0.	20098 0.1	2589	0.13098			4.581
		Volt. (in p.1	/			052 1.0		1.100			
Solutio			.) 1.78197				6117	0.13098	Solut	ion-2 80	06.184
		(p.0	.,		0.		/		Solui		

TABLE X

 $\underline{\text{Comparison}}\,\underline{\text{of the generation cost for IEEE-30 Bus system for normal and contingent cases}}$

OPF Method	Generation (Generation Cost (in \$/hr)				
	Case-1	Case-2				
Gradient projection method [17]	804.583	-				
Improved genetic algorithm [18]	800.81	812.33				
Enhanced genetic algorithm [5]	802.06	-				
EGA-Fuzzy	800.442	804.581				

V.CONCLUSION

In present paper an OPF method developed on adaptive EGA-Fuzzy approach is tried on 6 bus system and IEEE 30-bus system. Line flow constraints and lower voltage limits for load buses are successfully met under both normal and contingent states by employing penalty factors in determining fitness function. The proposed method shows superiority over other optimization methods, however the judicious selection of penalty factor settings is important as higher values of penalty factors may give suboptimal results. The proposed method can be generalized and easily extended to large-scale systems.

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