

# The symmetric solutions for three-point singular boundary value problems of differential equation

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**Abstract**—In this paper, by constructing a special operator and using fixed point index theorem of cone, we get the sufficient conditions for symmetric positive solution of a class of nonlinear singular boundary value problems with p-Laplace operator, which improved and generalized the result of related paper.

**Keywords**—Banach space, cone, fixed point index, singular differential equation, p-Laplace operator, symmetric solutions.

## I. INTRODUCTION

THE boundary value problems with p-Laplace operator arises in a variety of applied mathematics and physics, and they are widely applied in studying for non-newtonian fluid mechanics, cosmological physics, plasma physics, and theory of elasticity, etc. In recent years, some important results have been obtained by a variety of method(see[1-4]). On the other hand, the study for the symmetric and multiple solutions to this problem is more and more active (see[5-6]). In paper [5], Sun study for the problem

$$\begin{cases} (u)'' + a(t)f(t, u(t)) = 0, t \in (0, 1) \\ u(0) = \alpha u(\eta) = u(1), \end{cases}$$

where  $\alpha \in (0, 1), \eta \in (0, \frac{1}{2}]$ , by using spectrum theory, Sun get the existence of symmetric and multiple solution. But when  $p \neq 2$ ,  $\phi_p(u)$  is nonlinear, so the method of the paper [5] is not suitable to p-laplace operator. In paper [6], Tian and Liu study for the problem

$$\begin{cases} (\phi_p(u'))' + a(t)f(t, u(t)) = 0, t \in (0, 1) \\ u(0) = \alpha u(\eta) = u(1), \end{cases}$$

where  $\phi(s)$  is p-Laplace operator. Motivated by paper [5,6], we consider the existence of solution for the following problems:

$$\begin{cases} (\phi_p(u'))' + h_1(t)f(u, v) = 0, \\ (\phi_p(v'))' + h_2(t)g(u) = 0, \\ u(0) = \gamma u(\eta) = u(1), \\ v(0) = \gamma v(\eta) = v(1), \end{cases} \quad (1)$$

where  $t \in (0, 1), \gamma \in (0, 1), \eta \in (0, \frac{1}{2}]$ ,  $\phi(s)$  is a p-Laplace operator, i.e.  $\phi_p(s) = |s|^{p-2}s, p > 1$ . Obviously, if  $\frac{1}{p} + \frac{1}{q} = 1$ , then  $(\phi_p)^{-1} = \phi_q$ .

Compare with above paper, our method is different. By constructing a new operator, and using fixed point index theorem, we get the sufficient condition of the existence of symmetric solution, which improved and generalized the result of paper [5,6,7].

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In this paper, we always suppose that the following conditions hold:

(H<sub>1</sub>)  $f \in C([0, +\infty) \times [0, +\infty), [0, +\infty)), g \in C([0, +\infty), [0, +\infty))$ .

(H<sub>2</sub>)  $h_i \in C((0, 1), [0, +\infty)), h_i(t) = h_i(1-t), t \in (0, 1)$ , for any subinterval of  $(0, 1)$ ,  $h_i(t) \not\equiv 0$ , and  $\int_0^1 h_i(t)dt < +\infty (i = 1, 2)$ .

(H<sub>3</sub>) There exists  $\alpha \in (0, 1]$ , such that  $\liminf_{u \rightarrow +\infty} \frac{g(u)}{u^{\frac{p-1}{\alpha}}} = +\infty$  and  $\liminf_{v \rightarrow +\infty} \frac{f(u, v)}{v^{(p-1)\alpha}} > 0$  hold uniformly to  $u \in R^+$ .

(H<sub>4</sub>) There exists  $\beta \in (0, +\infty)$ , such that  $\limsup_{u \rightarrow 0^+} \frac{g(u)}{u^{\frac{p-1}{\beta}}} = 0$  and  $\limsup_{v \rightarrow 0^+} \frac{f(u, v)}{v^{(p-1)\beta}} < +\infty$  hold uniformly to  $u \in R^+$ .

(H<sub>5</sub>) There exists  $n \in (0, 1]$ , such that  $\liminf_{u \rightarrow 0^+} \frac{g(u)}{u^{\frac{p-1}{n}}} = +\infty$  and  $\liminf_{v \rightarrow 0^+} \frac{f(u, v)}{v^{(p-1)n}} > 0$  hold uniformly to  $u \in R^+$ .

(H<sub>6</sub>)  $f(u, v)$  and  $g(u)$  are nondecreasing with respect to  $u$  and  $v$ , and there exists  $R > 0$ , such that  $\frac{\gamma}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q(k_1(s))ds f(R, \frac{\gamma}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q(k_1(s))ds \times g(R)) < R$ , where  $k_i(s) = \int_s^{\frac{1}{2}} h_i(\tau)d\tau, i = 1, 2$ .

For convenience, we list the following definitions and lemmas:

**Definition 1.1** If  $u(t) = u(1-t), t \in [0, 1]$ , we call  $u(t)$  is symmetric in  $[0, 1]$ .

**Definition 1.2** If  $(u, v)$  is a positive solution of problem (1), and  $u, v$  is symmetric in  $[0, 1]$ , we call  $(u, v)$  is symmetric positive solution of problem (1).

**Definition 1.3** If  $u(\lambda t_1 + (1-\lambda)t_2) \geq \lambda u(t_1) + (1-\lambda)u(t_2)$ , we call  $u(t)$  is concave in  $[0, 1]$ .

Let  $E = C[0, 1]$ , define the norm  $\|u\| = \max_{t \in [0, 1]} |u(t)|$ , obviously  $(E, \|\cdot\|)$  is a Banach space.

Let  $K = \{u \in E | u(t) > 0, u(t) \text{ is a symmetric concave function}, t \in [0, 1]\}$ , then  $K$  is a cone in  $E$ . By (H<sub>1</sub>), (H<sub>2</sub>), the solution of problem (1) is equivalent to the solution of system of equation (2).

$$u(t) = \begin{cases} \int_0^t \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds, \\ 0 \leq t \leq \frac{1}{2}, \\ \int_t^1 \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds, \\ \frac{1}{2} \leq t \leq 1, \end{cases}$$

$$v(t) = \begin{cases} \int_0^t \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds, \\ 0 \leq t \leq \frac{1}{2}, \\ \int_t^1 \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds, \\ \frac{1}{2} \leq t \leq 1. \end{cases}$$

We define  $T : K \rightarrow E$  :

$$(Tu)(t) = \begin{cases} \int_0^t \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds, \\ 0 \leq t \leq \frac{1}{2}, \\ \int_t^1 \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds, \\ \frac{1}{2} \leq t \leq 1, \end{cases} \quad (3)$$

where

$$v(t) = \begin{cases} \int_0^t \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds, \\ 0 \leq t \leq \frac{1}{2}, \\ \int_t^1 \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds + \\ \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds, \\ \frac{1}{2} \leq t \leq 1. \end{cases} \quad (4)$$

Obviously  $Tu \in E$ , it is easy to show if  $T$  has fixed point  $u$ , then by (4), problem (1) has a solution  $(u, v)$ .

**Lemma 1.1** Let  $(H_1), (H_2)$ , then  $T : K \rightarrow K$  is completely continuous.

**Proof**  $\forall u \in K$ , by  $(H_1), (H_2)$ , we can get  $(Tu)(t) \geq 0, t \in [0, 1]$ .

$$v'(t) = \begin{cases} \phi_q(\int_t^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau), & 0 \leq t \leq \frac{1}{2}, \\ -\phi_q(\int_t^1 h_2(\tau) g(u(\tau)) d\tau), & \frac{1}{2} \leq t \leq 1, \end{cases}$$

correspondingly  $(\phi_p(v'))' = -h_2(t)g(u) \leq 0, 0 < t < 1$ , so  $v$  is concave in  $[0, 1]$ .

Next we show  $v$  is symmetric in  $[0, 1]$ .

When  $t \in [0, \frac{1}{2}]$ ,  $1-t \in [\frac{1}{2}, 1]$ , so

$$\begin{aligned} v(1-t) &= \int_{1-t}^1 \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds \\ &= \int_0^t \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds \\ &= v(t). \end{aligned}$$

Similarly, we have  $v(1-t) = v(t), t \in [\frac{1}{2}, 1]$ . So  $v$  is a symmetric concave function in  $[0, 1]$ .

$$(Tu)'(t) = \begin{cases} \phi_q(\int_t^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau), & 0 \leq t \leq \frac{1}{2}, \\ -\phi_q(\int_t^1 h_1(\tau) f(u(\tau), v(\tau)) d\tau), & \frac{1}{2} \leq t \leq 1, \end{cases}$$

(2) so  $(\phi_p((Tu)'))' = -h_1(t)f(u, v) \leq 0, 0 < t < 1$ , i.e.  $Tu$  is concave in  $[0, 1]$ .

Next we show  $Tu$  is symmetric in  $[0, 1]$ , when  $t \in [0, \frac{1}{2}]$ ,  $1-t \in [\frac{1}{2}, 1]$ , so

$$\begin{aligned} (Tu)(1-t) &= \int_{1-t}^1 \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds \\ &= \int_0^t \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds \\ &= (Tu)(t). \end{aligned}$$

Similarly, we have  $(Tu)(1-t) = (Tu)(t), t \in [\frac{1}{2}, 1]$ . so  $Tu$  is concave in  $[0, 1]$ , so  $TK \subset K$ . On the other hand, let  $D$  is a arbitrary bounded set of  $K$ , then there exist constant  $c > 0$ , such that  $D \subset \{u \in K \mid \|u\| \leq c\}$ . Let  $b = \max_{u \in [0, c]} g(u)$ , so  $\forall u \in D$ , we have

$$\begin{aligned} \|v\| &= \left| \int_0^{\frac{1}{2}} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds + \right. \\ &\quad \left. \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau) ds \right| \\ &\leq \frac{b^{q-1}}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau) d\tau) ds = a. \end{aligned}$$

Let  $L = \max_{u \in [0, c], v \in [0, a]} f(u, v)$ , so  $\forall u \in D$ , we have

$$\begin{aligned} \|Tu\| &= \left| \int_0^{\frac{1}{2}} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds \right. \\ &\quad \left. + \frac{\gamma}{1-\gamma} \int_0^\eta \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau) ds \right| \\ &\leq \frac{L^{q-1}}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau) d\tau) ds. \end{aligned}$$

$$\begin{aligned} \|(Tu)'\| &= \max\{|\phi_q(\int_0^{\frac{1}{2}} h_1(\tau)f(u(\tau), v(\tau))d\tau)|, \\ &|\phi_q(\int_{\frac{1}{2}}^1 h_1(\tau)f(u(\tau), v(\tau))d\tau)|\} \\ &\leq L^{q-1}\phi_q(\int_0^{\frac{1}{2}} h_1(\tau)d\tau). \end{aligned}$$

By Arzela-Ascoli theorem, we know  $TD$  is compact set. By Lebesgue dominated convergence theorem, it is easy to show  $T$  is continuous in  $K$ , so  $T : K \rightarrow K$  is completely continuous.

**Lemma 1.2** For any  $0 < \varepsilon < \frac{1}{2}$ ,  $u \in K$ , we have

- (1)  $u(t) \geq \|u\|t(1-t)$ ,  $\forall t \in [0, 1]$ ;
- (2)  $u(t) \geq \varepsilon^2\|u\|$ ,  $t \in [\varepsilon, 1-\varepsilon]$ . (the proof is elementary, we omit it.)

**Lemma 1.3**(see [8]) Let  $K$  is a cone of  $E$  in Banach space,  $\Omega_1$  and  $\Omega_2$  are open subsets in  $E$ ,  $\theta \in \Omega_1$ ,  $\overline{\Omega_1} \subset \Omega_2$ , and  $T : K \cap (\overline{\Omega_2} \setminus \Omega_1) \rightarrow K$  is a completely continuous operator, and satisfy one of the following conditions:

$$(1) \|Tx\| \leq \|x\|, \forall x \in K \cap \partial\Omega_1, \|Tx\| \geq x, \forall x \in K \cap \partial\Omega_2,$$

$$(2) \|Tx\| \geq \|x\|, \forall x \in K \cap \partial\Omega_1, \|Tx\| \leq x, \forall x \in K \cap \partial\Omega_2,$$

then  $A$  has at least one fixed point in  $K \cap (\Omega_2 \setminus \Omega_1)$ .

**Lemma 1.4**(see [9]) Let  $K$  is a cone of  $E$  in Banach space,  $K_r = \{x \in K \mid \|x\| \leq r\}$ , suppose  $A : K_r \rightarrow K$  is a completely continuous, and satisfy  $Tx \neq x$ ,  $\forall x \in \partial K_r$ ,

- (1) If  $\|Tx\| \leq x$ ,  $\forall x \in \partial K_r$ , then  $i(T, K_r, K) = 1$ ,
- (2) If  $\|Tx\| \geq x$ ,  $\forall x \in \partial K_r$ , then  $i(T, K_r, K) = 0$ .

## II. CONCLUSION

**Theorem 2.1** Suppose  $(H_1) - (H_4)$  hold, then problem (1) has at least one positive solution.

**Proof** By  $(H_3)$ , there exist  $\nu$  and a sufficient large number  $M > 0$ , such that

$$f(u, v) \geq \nu^{p-1}v^{(p-1)\alpha}, \forall u \in R^+, v > M, \quad (5)$$

$$g(u) \geq C_0^{p-1}u^{\frac{p-1}{\alpha}}, \forall u > M, \quad (6)$$

where  $C_0 = \max\{(\frac{\gamma}{1-\gamma} \int_{\varepsilon}^{\eta} \phi_q(k_2(s))ds)^{-1}, (\frac{2}{\nu\gamma^{\alpha}\varepsilon^2(\frac{1}{1-\gamma} \int_0^{\eta} \phi_q(k_1(s))^{\alpha+1}})^{\frac{1}{\alpha}}\}$ . Let  $N = (M+1)\varepsilon^{-2}$ , if  $u \in K \cap \partial K_N$ , by Lemma 2,  $\min_{\varepsilon \leq t \leq 1-\varepsilon} u(t) \geq \varepsilon^2\|u\| = \varepsilon^2N = M+1$ , by (3)-(6) and the symmetric property, for any  $t \in [\varepsilon, 1-\varepsilon]$

$$\begin{aligned} v(t) &= \int_0^t \phi_q(\int_{\frac{1}{2}}^s h_2(\tau)g(u(\tau))d\tau)ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau)g(u(\tau))d\tau)ds \\ &\geq \frac{\gamma}{1-\gamma} \int_0^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau)g(u(\tau))d\tau)ds \\ &\geq \frac{\gamma}{1-\gamma} \int_{\varepsilon}^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau)g(u(\tau))d\tau)ds \\ &\geq \frac{C_0\gamma}{1-\gamma} \int_{\varepsilon}^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau)(u(\tau)^{\frac{p-1}{\alpha}})d\tau)ds \\ &\geq \frac{C_0\gamma}{1-\gamma} \int_{\varepsilon}^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau))d\tau)ds(\varepsilon^2\|u\|)^{\frac{1}{\alpha}} \\ &\geq \frac{C_0\gamma}{1-\gamma} \int_{\varepsilon}^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_2(\tau))d\tau)ds(M+1)^{\frac{1}{\alpha}} \\ &\geq M+1. \end{aligned}$$

$$\begin{aligned} \|Tu\| &= |\int_0^{\frac{1}{2}} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)f(u(\tau), v(\tau))d\tau)ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)f(u(\tau), v(\tau))d\tau)ds,| \\ &\geq \frac{1}{1-\gamma} \int_0^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)f(u(\tau), v(\tau))d\tau)ds, \\ &\geq \frac{\nu}{1-\gamma} \int_0^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)v(\tau)^{(p-1)\alpha}d\tau)ds, \\ &\geq \frac{\nu}{1-\gamma} \int_{\varepsilon}^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)d\tau)ds \times \\ &\quad (\frac{C_0\gamma}{1-\gamma} \int_{\varepsilon}^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)d\tau)ds)^{\alpha}\varepsilon^2\|u\| \\ &= \nu C_0^{\alpha}\gamma^{\alpha}\varepsilon^2(\frac{1}{1-\gamma} \int_0^{\eta} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)d\tau)ds)^{\alpha+1}\|u\| \\ &\geq 2\|u\|, \end{aligned}$$

so  $\|Tu\| > \|u\|$ ,  $\forall u \in K \cap K_N$ , by lemma 1.4, we can get

$$i(T, K \cap K_N, K) = 0. \quad (7)$$

On the other hand, by the second limit of  $H_4$ , there exists a sufficient small number  $r_1 \in (0, 1)$  such that

$$C_1^{p-1} = \sup\{\frac{f(u, v)}{v^{(p-1)\beta}} \mid u \in R^+, v \in (0, r_1]\} < +\infty. \quad (8)$$

Let  $\varepsilon = \min\{\frac{r_1(1-\gamma)}{\int_0^{\frac{1}{2}} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)d\tau)ds}, (\frac{C_1}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q(\int_s^{\frac{1}{2}} h_1(\tau)d\tau)ds)^{\frac{-\beta-1}{\beta}}\}$ , by the first limit of  $H_4$ , there exist a sufficient small number  $r_2 \in (0, 1)$  such that

$$g(u) \leq \varepsilon^{p-1}u^{\frac{p-1}{\beta}}, \forall u \in [0, r_2]. \quad (9)$$

Take  $r = \min\{r_1, r_2\}$ , by (9), we can get

$$\begin{aligned} v(t) &= \int_0^{\frac{1}{2}} \phi_q \left( \int_s^t h_2(\tau) g(u(\tau)) d\tau \right) ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau \right) ds \\ &\leq \frac{1}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau \right) ds \\ &\leq \frac{\varepsilon}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_2(\tau) d\tau \right) ds \|u\|^{\frac{1}{\beta}} \\ &\leq r_1^{1+\frac{1}{\beta}} < r_1, \forall u \in K \cap \partial K_r, s \in [0, 1]. \end{aligned}$$

By (8), we can get

$$\begin{aligned} \|Tu\| &\leq \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau \right) ds + \\ &\quad \frac{\gamma}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau \right) ds, \\ &\leq \frac{C_1}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \times \\ &\quad \left( \frac{\varepsilon}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \right)^\beta \|u\| \\ &= C_1 \varepsilon^\beta \left( \frac{1}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \right)^{\beta+1} \|u\| \\ &\leq \|u\|, \forall u \in K \cap \partial K_r, t \in [0, 1]. \end{aligned}$$

So  $\|Tu\| \leq \|u\|, \forall u \in K \cap \partial K_r$ , by lemma 1.4, we get

$$i(T, K \cap K_r, K) = 1. \quad (10)$$

By lemma 1.5,  $T$  has at least one fixed point in  $K \cap (\overline{K_N} \setminus K_r)$ , so problem (1) has at least a system positive solution.

**Theorem 2.2** Suppose  $(H_1), (H_2), (H_3), (H_5), (H_6)$  hold, then problem (1) has at least two systems positive solutions.

**Proof** By  $(H_5)$ , there exists  $\mu > 0$  and a sufficient small number  $\xi \in (0, 1)$ , such that

$$f(u, v) \geq \mu^{p-1} v^{n(p-1)}, \forall u \in R^+, 0 \leq v \leq \xi, \quad (11)$$

$$g(u) \geq (C_2 u)^{\frac{p-1}{n}}, \forall 0 \leq u \leq \xi, \quad (12)$$

where

$$C_2 = 2 \left( \frac{\mu \varepsilon^2}{1-\gamma} \right)^n \int_\epsilon^\eta \phi_q(k_1(s)) ds \int_\epsilon^\eta (\phi_q(k_2(s)))^n ds)^{-1}$$

since  $g \in C(R^+, R^+)$ ,  $g(0) \equiv 0$ , so there exists  $\sigma \in (0, \xi)$  such that  $\forall u \in [0, \sigma]$ , we have

$$g(u) \leq \left( \frac{1}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \right)^{-1},$$

this imply

$$\begin{aligned} v(t) &\leq \frac{1}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau \right) ds \\ &\leq \xi, \forall u \in K \cap \partial K_\sigma. \end{aligned} \quad (13)$$

By using Jensen inequality,  $0 < q \leq 1$ , and (11)-(13), we can get

$$\begin{aligned} (Tu)(\tfrac{1}{2}) &\geq \frac{\mu}{1-\gamma} \int_\epsilon^\eta \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \times \\ &\quad \left( \frac{\gamma}{1-\gamma} \int_\epsilon^\eta \phi_q \left( \int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau \right) ds \right)^n \\ &\geq \frac{\mu}{1-\gamma} \int_\epsilon^\eta \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \times \\ &\quad \left( \frac{\gamma}{1-\gamma} \right)^n \int_\epsilon^\eta \left( \phi_q \left( \int_s^{\frac{1}{2}} h_2(\tau) g(u(\tau)) d\tau \right) \right)^n ds \\ &\geq \frac{\mu C_2 \varepsilon^2}{1-\gamma} \left( \frac{\gamma}{1-\gamma} \right)^n \int_\epsilon^\eta \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \times \\ &\quad \int_\epsilon^\eta \left( \phi_q \left( \int_s^{\frac{1}{2}} h_2(\tau) d\tau \right) \right)^n ds \|u\| \\ &= 2 \|u\|, \forall u \in K \cap \partial K_\sigma. \end{aligned}$$

So  $\|Tu\| > \|u\|, \forall u \in K \cap \partial K_\sigma$ , by lemma 1.4, we can get

$$i(T, K \cap K_\sigma, K) = 0. \quad (14)$$

We can choose  $N > R > \sigma$ , such that (7),(14) hold together.

On the other hand by (3),(4) and  $H_6$  we can get

$$\begin{aligned} (Tu)(t) &< \frac{1}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) f(u(\tau), v(\tau)) d\tau \right) ds \\ &\leq \frac{\gamma}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds \times \\ &\quad f(R, \frac{\gamma}{1-\gamma} \int_0^{\frac{1}{2}} \phi_q \left( \int_s^{\frac{1}{2}} h_1(\tau) d\tau \right) ds g(R)) \\ &< R, \forall u \in K \cap K_R, \forall t \in [0, 1]. \end{aligned}$$

So for any  $u \in K \cap K_R$ , by lemma 1.4, we can get

$$i(T, K \cap K_R, K) = 1. \quad (15)$$

By (7),(14),(15), we have

$$\begin{aligned} &i(T, K \cap (K_N \setminus \overline{K_R}), K) \\ &= i(T, K \cap K_N, K) - i(T, K \cap K_R, K) \\ &= -1. \\ &i(T, K \cap (K_R \setminus \overline{K_\sigma}), K) \\ &= i(T, K \cap K_R, K) - i(T, K \cap K_\sigma, K) \\ &= 1 \end{aligned}$$

So  $T$  have at least two fixed points in  $K \cap (K_N \setminus \overline{K_R})$  and  $K \cap (K_R \setminus \overline{K_\sigma})$ , by (4), problem (1) has at least two system solutions.

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