# A Multi Task Scheme to Monitor Multivariate Environments Using Artificial Neural Network 

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#### Abstract

When an assignable cause(s) manifests itself to a multivariate process and the process shifts to an out-of-control condition, a root-cause analysis should be initiated by quality engineers to identify and eliminate the assignable cause(s) affected the process. A root-cause analysis in a multivariate process is more complex compared to a univariate process. In the case of a process involved several correlated variables an effective root-cause analysis can be only experienced when it is possible to identify the required knowledge including the out-of-control condition, the change point, and the variable(s) responsible to the out-of-control condition, all simultaneously. Although literature addresses different schemes to monitor multivariate processes, one can find few scientific reports focused on all the required knowledge. To the best of the author's knowledge this is the first time that a multi task model based on artificial neural network (ANN) is reported to monitor all the required knowledge at the same time for a multivariate process with more than two correlated quality characteristics. The performance of the proposed scheme is evaluated numerically when different step shifts affect the mean vector. Average run length is used to investigate the performance of the proposed multi task model. The simulated results indicate the multi task scheme performs all the required knowledge effectively.


Keywords—Artificial neural network, Multivariate process, Statistical process control, Change point.

## I. Introduction

LITERATURE indicates statistical process control (SPC) رapproach could play an essential role to control the variability of processes. Among the SPC methods, control charts are known as an effective method to monitor a process behavior when SPC is approached (For more details the reader is directed to Montgomery [1]). Control charts first proposed by Shewhart [2] when he launched a new approach to monitor variability of a process. The importance of the process involved several correlated variables led researchers to develop the Shewhart control charts. Hotelling [3] considered multivariate processes and proposed T 2 procedure. The major deficiency of T2 Hotelling method is relatively insensitive when a small or a moderate change(s) affects the process. To overcome the deficiency several authors contributed to develop multivariate cumulative sum (MCUSUM) and multivariate exponential weighted moving average (MEWMA) schemes. Several authors including Woodall and Ncube [4], Healy [5], Crosier [6], Pignatiello and Runger [7], Ngai and Zhang [8], Chan and Zhang [9], Qiu and Hawkins [10], [11], and Runger and Testik [12] focused on MCUSUM.

[^0]Many researcher such Lowry et al. [13], Rigdon [14], Yumin [15], Runger and Prabhu [16], Kramer and Schmid [17], Prabhu and Runger [18], Fasso [19], Borror et al. [20], Runger et al. [21], Tseng et al. [22], Yeh et al. [23], Testik et al. [24], Testik and Borror [25] and Chen et al. [26] contributed to MEWMA performance. The major capability of all the control charts introduced in literature is referred to as detecting the out-of-control condition when an assignable cause takes a place in the process. However when a process involved multivariable shifts to an out-of-control condition a quality engineer to an effective root-cause analysis needs to know the change point and the variable(s) contributed to the out-ofcontrol condition. Change point is the time when the process really shifts to an out-of-control condition (For more details the reader is directed to Atashgar [27]). A control chart relative to its sensitivity signals with a delay after the process really shifts to an out-of-control condition. The delay is referred to as the out-of-control average run length (ARL). Literature involves several different schemes proposed to identify the required knowledge separately. Mason et al. [28], Apaarisi et al. [29] and Niaki and Abbasi [30] focused on to diagnose the variable responsible to the out-of-control condition, however, the authors including Nedumaran et al. [31] and Noorossana et al. [32] contributed to identify the change point in the mean vector of a multivariate process. Noorossana et al. [33] proposed an artificial neural network to identify all the important knowledge leading to an effective root-cause analysis. Although the scientific report addresses an effective performance, the proposed model does not allow one to use it in a process involved more than two variables. In this paper a multi task scheme based on a supervised ANN is proposed to provide all the required knowledge for multivariate environments. The multi task model is capable to identify the change point and diagnose the quality characteristic(s) responsible to the out-of-control condition at the same time that the model signals an out-of-control condition. The report addresses an effective performance for the model when the mean vector of a process involved three quality characteristics affecting different step shift magnitudes departs to an out-of-control condition.

In the next section the proposed model is introduced. The procedure used to train the ANN model and the results of the performance evaluation of the proposed multi task scheme are discussed in Section III. Finally, author's concluding remarks are provided in Section IV.

## II. The Proposed Multi Task Scheme

Assume $\mathrm{X} 1, \mathrm{X} 2, \ldots \mathrm{X} \tau, \mathrm{X} \tau+1, \ldots, \mathrm{XT}$ are independent vectors of a multivariate process observations which follow an
identical normal distribution with mean vector $\boldsymbol{\mu}_{0}$ $=\left(\mu_{01}, \mu_{02}, \ldots, \mu_{0 p}\right)$ and covariance matrix $\Sigma$. Assuming that after an unknown time $\tau$ a disturbance of a step change type affects the mean vector, the process shifts to an out-of-control condition at time $\tau$ but the shift is detected at time T. The out-of-control condition is detected when $\chi 2$ statistic is computed as the following equation 1 and compared to a pre-specified control limit:

$$
\begin{equation*}
\chi^{2}=n\left(\bar{X}-\mu_{0}\right)^{\prime} \Sigma^{-1}\left(\bar{X}-\mu_{0}\right) \tag{1}
\end{equation*}
$$

Furthermore, assume $\boldsymbol{X}=\left(X_{1}, X_{2}, \ldots, X_{p}\right)$ indicates a $p \times 1$ random vector of the quality characteristics. In this case $\tau$ is considered as the change point or the time when the disturbance first really has affected the multivariate normal process. However the control chart with a delay signals at time T . In this case also the knowledge of which of the quality characteristics has contributed to the out-of-control condition is known as a valuable factor for the quality engineers at the time when they want to start to identify the assignable cause.

The proposed multi task scheme follows modularity approach. The ANN model after training will be able to detect an out-of-control condition, identify the change point $\tau$ and the variable(s) contributed to the out-of-control condition at the same time. In this research, supervised learning is approached to allow the ANN storing the knowledge to modify weights and biases. Multi layer perceptron (MLP) is used for the proposed model. Literature indicates MLP could provide an effective performance in which the pattern recognition is approached by researchers. The specification of ANN as shown in Table I contains two network modules with different layers. However after training Network A will be able to detect the shift in the mean vector along with diagnosing the variable(s) responsible to the shift and Network $B$ will be able to identify the time when really the shift occurs in the process, i.e. the change point. In this research 24389 different combinations including one combination of incontrol condition and 24388 combinations of out-of-control condition are used to train the proposed multi task model. The input layer of both networks contains 36 neurons, however Network A and Network B involve 7 and 1 neurons for the output layers, respectively. Table II shows the cases corresponding to the different conditions might be signaled by Network 1, where $S$ indicates to the shift. For example when Network 1 signals 1 by the first neuron, it indicates that the process has shifted to the out-of-control and the first variable has contributed to the condition. Furthermore when number 1 appears in neuron 6 it indicates that the process works in an out-of-control condition and the quality specifications 2 and 3 are contributed to the unnatural condition.

## III. Networks Training and Performance Evaluation

In this research, to perform the required training and data of performance evaluation Monte Carlo simulation is used for each ANN. The equation used here to generate the data sets is as follow:

$$
\begin{equation*}
X_{t}=\mu+n_{t}+k \sigma \tag{2}
\end{equation*}
$$

here t indicates the sampling time and $\boldsymbol{X}_{\boldsymbol{t}}$ represents an independent random vector corresponding to the quality characteristics measured at time t . When the process is in control, $\boldsymbol{X}_{\boldsymbol{t}}$ follows a normal distribution with mean vector $\boldsymbol{\mu}$ and covariance matrix $\Sigma$. In (2), $\mathrm{n}^{t}$ indicates the variation corresponding to common cause at time t which follows $N(Q, \Sigma)$. In the equation vector k represents the shift magnitude.
In this research four phases including standardization, zoning, permutation and scaling discussed by Atashgar and Noorossana [34] are used to improve the performance of each network prior to introducing data sets to the networks. Equation (2) is used to simulate the training data set to provide supervised learning approached in this research. Furthermore, to train the model the subinterval approach introduced first by Atashgar and Noorossana [34] is used here. Table III shows the breakdown of the intervals and the number of training iterations for each subinterval. For more details the reader is directed to Atashgar and Noorossana [34].

To evaluate the performance of the model using different shifts magnitude the moving window approach is considered here.

TABLE I
SPECIFICATIONS OF THE NETWORKS

| SPECIFICATIONS OF THE NETWORKS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Network | No. of <br> Hidden <br> Layer | No. of Hidden <br> Layer Neurons | No. of Output <br> Layer Neurons | Training <br> Algorithm |
| A | 2 | 17 | 7 | Trainbfg |
| B | 2 | 14 | 1 | Trainbfg |

TABLE II
The Concept of the Signals in Output Layer

| Quality specification |  |  | output |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\chi_{1}$ | $X_{2}$ | $\chi_{3}$ | 1 | 23 | 34 | 5 | 6 | 7 |
| S | - | - | 1 | 0 | 00 | 0 | 0 | 0 |
| - | S | - | 0 | 10 | 00 | 0 | 0 | 0 |
| - | - | S | 0 | 01 | 10 | 0 | 0 | 0 |
| S | S | - | 0 | 0 | 01 | 0 | 0 | 0 |
| S | - | S | 0 | 0 | 00 | 1 | 0 |  |
| - | S | S | 0 | 0 | 00 | 0 | 1 | 0 |
| S | S | S |  | 00 | 00 | 0 | 0 |  |

TABLE III
SUBintervals of The Networks

|  | $\begin{gathered} \hline \text { No. } \\ 1 \end{gathered}$ | Subinterval | No. of combinations 21952 | No. of iterations 2 | $\begin{aligned} & \hline \hline \text { Total } \\ & 43904 \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 2 |  | 2352 | 45 | 105840 |
| Network 1 |  |  |  |  |  |
|  | 3 |  | 84 | 190 | 15960 |
|  | 4 | In-control | 1 | 50000 | 50000 |
|  | Total |  | 24389 |  | 215704 |
|  | 1 |  | 21952 | 3 | 65856 |
|  | 2 |  | 2352 | 47 | 110544 |
| Network 2 |  |  |  |  |  |
|  | 3 |  | 84 | 190 | 15960 |
|  | 4 | In-control | 1 | 30000 | 30000 |
|  | Total |  | 24389 |  | 222360 |

Moving window is discussed by Guh [35] and Hwarng [36]. In this evaluation is assumed that the first 100 data set of observation are generated from an in-control condition. Beginning with time 101, a disturbance of step type occurs in the process and affects the mean vector. Average run length and correct classification criterions using 10000 iterations for each combination shown in Table IV which lead to an out-ofcontrol condition is considered to evaluate the performance of the model. Table IV shows the results in term discussed before. Correct classification percentage is calculated using the following equation:

Correct Classification \% $=\left(1-\frac{e c}{n}\right) \times 100$
where, ec and n variables indicate to the number of error classifications and the number of inputs, respectively.

TABLE IV
Performance Report of the Proposed Model under Different Shifts

| Performance Report of the Proposed Model under Different Shifts |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Shift Combination | (-3,-3,-3) | (-2,-3,-3) | (-1,-3,-3) | (0,-3,-3) | (1,-3,-3) | (2,-3,-3) | (3,-3,-3) | (-3,-3,-2) | $(-2,-3,-2)$ |
| Out-of-Control ARL | 2.7795 | 3.2421 | 3.8447 | 4.4187 | 4.2829 | 3.2214 | 2.7907 | 3.2085 | 3.7561 |
| Correct Classification \% | 94.70 | 89.65 | 62.64 | 85.05 | 58.67 | 86.58 | 92.48 | 90.24 | 92.24 |
| Change Point | 99.9891 | 100.0554 | 100.1638 | 100.2211 | 100.2059 | 100.1117 | 100.0407 | 100.1920 | 100.3396 |
| Standard Error | 0.0043 | 0.0053 | 0.0067 | 0.0072 | 0.0070 | 0.0061 | 0.0052 | 0.0068 | 0.0089 |
| Shift Combination | (-1,-3,-2) | (0,-3,-2) | (1,-3,-2) | (2,-3,-2) | (3,-3,-2) | (-3,-3,-1) | (-2,-3,-1) | (-1,-3,-1) | (0,-3,-1) |
| Out-of-Control ARL | 4.9042 | 5.2640 | 5.3019 | 3.7393 | 3.1644 | 4.0796 | 5.0997 | 8.7030 | 11.7287 |
| Correct Classification \% | 73.73 | 89.10 | 69.54 | 89.52 | 87.27 | 64.31 | 73.95 | 80.74 | 91.58 |
| Change Point | 100.6238 | 100.8058 | 100.7503 | 100.5798 | 100.4585 | 100.5577 | 101.0802 | 102.1909 | 103.2777 |
| Standard Error | 0.0121 | 0.0141 | 0.0141 | 0.0122 | 0.0112 | 0.0106 | 0.0167 | 0.0296 | 0.0412 |
| Shift Combination | (1,-3,-1) | (2,-3,-1) | (3,-3,-1) | (-3,-3,0) | $(-2,-3,0)$ | (-1,-3,0) | $(1,-3,0)$ | $(2,-3,0)$ | $(3,-3,0)$ |
| Out-of-Control ARL | 9.5546 | 4.9334 | 3.9116 | 4.2779 | 5.3158 | 12.2505 | 11.4519 | 5.2042 | 4.2185 |
| Correct Classification \% | 77.68 | 69.82 | 59.09 | 88.96 | 89.64 | 90.75 | 92.72 | 91.47 | 90.22 |
| Change Point | 103.1379 | 102.3401 | 101.9630 | 100.7416 | 101.5805 | 104.3854 | 107.4700 | 104.5669 | 103.5188 |
| Standard Error | 0.0404 | 0.0326 | 0.0352 | 0.0124 | 0.0214 | 0.0541 | 0.0863 | 0.0580 | 0.0604 |
| Shift Combination | $(-3,-3,1)$ | $(-2,-3,1)$ | $(-1,-3,1)$ | $(0,-3,1)$ | $(1,-3,1)$ | $(2,-3,1)$ | $(3,-3,1)$ | (-3,-3,2) | (-2,-3,2) |
| Out-of-Control ARL | 4.2815 | 5.2504 | 8.9664 | 12.2681 | 9.2380 | 5.4125 | 4.3717 | 3.2651 | 3.7689 |
| Correct Classification \% | 63.27 | 73.66 | 82.99 | 90.77 | 79.30 | 72.48 | 64.81 | 89.50 | 92.32 |
| Change Point | 100.5536 | 101.0191 | 102,0209 | 102.7315 | 102.5966 | 101.9981 | 101.6383 | 100.1738 | 100.2930 |
| Standard Error | 0.0106 | 0.0162 | 0.0283 | 0.0356 | 0.0348 | 0.0270 | 0.0227 | 0.0066 | 0.0084 |
| Shift Combination | (-1,-3,2) | $(0,-3,2)$ | $(1,-3,2)$ | $(2,-3,2)$ | $(3,-3,2)$ | $(-3,-3,3)$ | $(-2,-3,3)$ | (-1,-3,3) | $(0,-3,3)$ |
| Out-of-Control ARL | 5.1677 | 5.2527 | 5.3861 | 3.6636 | 3.1700 | 2.8054 | 3.2846 | 4.3620 | 4.1373 |
| Correct Classification \% | 73.80 | 91.52 | 71.26 | 91.48 | 90.21 | 94.51 | 90.14 | 61.37 | 92.86 |
| Change Point | 100.4322 | 100.5110 | 100.5047 | 100.4534 | 100.4011 | 99.9812 | 99.9990 | 100.0091 | 100.0304 |
| Standard Error | 0.0102 | 0.0111 | 0.0108 | 0.0106 | 0.0096 | 0.0040 | 0.0044 | 0.0048 | 0.0050 |
| Shift Combination | $(1,-3,3)$ | $(2,-3,3)$ | $(3,-3,3)$ | (-3-2,-3) | (-2,-2,-3) | (-1,-2,-3) | (0,-2,-3) | $(1,-2,-3)$ | (2,-2,-3) |
| Out-of-Control ARL | 4.8552 | 3.2115 | 2.7494 | 2.7830 | 2.2582 | 3.8207 | 4.4350 | 4.3003 | 3.2470 |
| Correct Classification \% | 60.54 | 91.65 | 94.70 | 94.92 | 90.03 | 62.08 | 85.10 | 58.88 | 87.20 |
| Change Point | 100.0239 | 100.0093 | 100.0000 | 99.9844 | 100.0543 | 100.1675 | 100.2110 | 100.2022 | 100.1024 |
| Standard Error | 0.0049 | 0.0047 | 0.0045 | 0.0042 | 0.0053 | 0.0067 | 0.0072 | 0.0071 | 0.0062 |
| Shift Combination | (3,-2,-3) | (-3,-2,-2) | (-2,-2,-2) | (-1,-2,-2) | (0,-2,-2) | (1,-2,-2) | (2,-2,-2) | $(3,-2,-2)$ | (-3,-2,-1) |
| Out-of-Control ARL | 2.7797 | 3.2272 | 3.7620 | 4.8934 | 5.2302 | 5.3214 | 3.7143 | 3.1863 | 4.1342 |
| Correct Classification \% | 92.15 | 90.81 | 91.93 | 73.62 | 89.23 | 70.42 | 89.29 | 87.97 | 64.94 |
| Change Point | 100.0397 | 100.2057 | 100.3871 | 100.6157 | 100.7987 | 100.7345 | 100.5777 | 100.4353 | 100.5576 |
| Standard Error | 0.0051 | 0.0068 | 0.0093 | 0.0122 | 0.0141 | 0.0136 | 0.0120 | 0.0107 | 0.0107 |
| Shift Combination | (-2,-2,-1) | (-1,-2,-1) | (0,-2,-1) | (1,-2,-1) | (2,-2,-1) | (3,-2,-1) | $(-3,-2,0)$ | $(-2,-2,0)$ | (-1,-2,0) |
| Out-of-Control ARL | 5.0903 | 8.6491 | 11.6994 | 9.5067 | 4.9269 | 3.8793 | 4.2950 | 5.3485 | 12.1269 |
| Correct Classification \% | 74.03 | 80.68 | 92.03 | 78.04 | 69.97 | 59.12 | 88.72 | 90.19 | 90.59 |
| Change Point | 101.0637 | 102.2911 | 103.1901 | 103.0740 | 102.3006 | 102.0233 | 100.7418 | 101.6163 | 104.3824 |
| Standard Error | 0.0165 | 0.0307 | 0.0394 | 0.0391 | 0.0323 | 0.0365 | 0.0124 | 0.0213 | 0.0541 |
| Shift Combination | $(1,-2,0)$ | $(2,-2,0)$ | $(3,-2,0)$ | $(-3,-2,1)$ | $(-2,-2,1)$ | $(-1,-2,1)$ | $(0,-2,1)$ | $(1,-2,1)$ | $(2,-2,1)$ |
| Out-of-Control ARL | 11.5195 | 5.1740 | 4.2370 | 4.2813 | 5.2293 | 9,0930 | 12.3464 | 9.3376 | 5.4249 |
| Correct Classification \% | 92.55 | 91.44 | 90.10 | 62.43 | 72.89 | 83.13 | 90.79 | 80.26 | 72.79 |
| Change Point | 107.5967 | 104.5857 | 103.4334 | 100.5471 | 101.0193 | 102.0006 | 102.7529 | 102.6865 | 102.0562 |
| Standard Error | 0.0892 | 0.0585 | 0.0592 | 0.0106 | 0.0163 | 0.0284 | 0.0361 | 0.0361 | 0.0278 |
| Shift Combination | (3,-2,1) | (-3,-2,2) | (-2,-2,2) | $(-1,-2,2)$ | (0,-2,2) | $(1,-2,2)$ | $(2,-2,2)$ | $(3,-2,2)$ | (-3,-2,3) |
| Out-of-Control ARL | 4.3927 | 3.2693 | 3.7615 | 5.1369 | 5.2310 | 5.4206 | 3.6625 | 3.1863 | 2.8148 |
| Correct Classification \% | 64.01 | 89.70 | 92.17 | 73.00 | 91.84 | 71.71 | 91.38 | 90.14 | 95.10 |
| Change Point | 101.6681 | 100.1808 | 100.3059 | 100.4533 | 100.5116 | 100.4977 | 100.4502 | 100.3834 | 99.9661 |
| Standard Error | 0.0229 | 0.0068 | 0.0084 | 0.0103 | 0.0112 | 0.0110 | 0.0104 | 0.0096 | 0.0040 |
| Shift Combination | $(-2,-2,3)$ | $(-1,-2,3)$ | (0,-2,3) | $(1,-2,3)$ | $(2,-2,3)$ | $(3,-2,3)$ | (-3,-1,-3) | (-2,-1,-3) | (-1,-1,-3) |
| Out-of-Control ARL | 3.2976 | 4.4345 | 4.1614 | 4.8143 | 3.1986 | 2.7455 | 2.8013 | 1.2598 | 3.8601 |
| Correct Classification \% | 90.61 | 61.44 | 92.57 | 58.98 | 90.48 | 94.64 | 94.83 | 90.57 | 63.05 |
| Change Point | 99,9877 | 100.0263 | 100.0343 | 100.278 | 100.0155 | 99.9973 | 99.9865 | 100.0635 | 100.1680 |
| Standard Error | 0.0044 | 0.0048 | 0.0050 | 0.0049 | 0.0047 | 0.0045 | 0.0042 | 0.0054 | 0.0065 |
| Shift Combination | (0,-1,-3) | (1,-1,-3) | (2,-1,-3) | (3,-1,-3) | (-3,-1,-2) | (-2,-1,-2) | (-1,-1,-2) | (0,-1,-2) | (1,-1,-2) |
| Out-of-Control ARL | 4.4288 | 4.2816 | 3.2319 | 2.7754 | 3.2135 | 3.7355 | 4.8846 | 5.2090 | 5.3270 |
| Correct Classification \% | 85.82 | 58.30 | 86.52 | 92.60 | 90.60 | 91.99 | 72.57 | 89.49 | 69.85 |
| Change Point | 100.2160 | 100.1892 | 100.1005 | 100.0430 | 100.1958 | 100.4332 | 100.6163 | 100.6163 | 100.7375 |
| Standard Error | 0.0073 | 0.0070 | 0.0061 | 0.0051 | 0.0068 | 0.0088 | 0.0121 | 0.0137 | 0.0138 |
| Shift Combination | (2,-1,-2) | (3,-1,-2) | (-3,-1,-1) | (-2,-1,-1) | (-1,-1,-1) | (0,-1,-1) | (1,-1,-1) | (2,-1,-1) | (3,-1,-1) |
| Out-of-Control ARL | 3.7328 | 3.1893 | 4.0791 | 5.1150 | 8.5512 | 11.9294 | 9.5243 | 4.9688 | 3.8686 |
| Correct Classification \% | 89.09 | 88.10 | 64.17 | 74.14 | 80.76 | 92.21 | 77.94 | 69.99 | 58.90 |
| Change Point | 100.5788 | 100.4548 | 100.5596 | 101.0822 | 102.2248 | 103.3391 | 103.1184 | 102.2371 | 102.0065 |
| Standard Error | 0.0120 | 0.0112 | 0.0104 | 0.0168 | 0.0294 | 0.0410 | 0.0400 | 0.0326 | 0.0352 |


| Shift Combination | (-3,-1,0) | (-2,-1,0) | (-1,-1,0) | (1,-1,0) | (2,-1,0) | (3,-1,0) | (-3,-1,1) | $(-2,-1,1)$ | (-1,-1,1) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Out-of-Control ARL | 4.2947 | 5.3346 | 12.3297 | 11.5599 | 5.1869 | 4.2345 | 4.2938 | 5.2138 | 8.9909 |
| Correct Classification \% | 89.16 | 90.46 | 90.79 | 92.66 | 91.28 | 89.57 | 63.14 | 73.79 | 83.11 |
| Change Point | 100.7481 | 101.6111 | 104.3996 | 107.5090 | 104.6273 | 103.5005 | 100.5566 | 101.0301 | 101.9612 |
| Standard Error | 0.0124 | 0.0214 | 0.0543 | 0.0895 | 0.0567 | 0.0618 | 0.0106 | 0.0164 | 0.0279 |
| Shift Combination | (0,-1,1) | (1,-1,1) | (2,-1,1) | (3,-1,1) | (-3,-1,2) | (-2,-1,2) | (-1,-1,2) | (0,-1,2) | (1,-1,2) |
| Out-of-Control ARL | 12.2183 | 9.3191 | 5.3998 | 4.4103 | 3.2768 | 3.7710 | 5.1327 | 5.2888 | 5.4527 |
| Correct Classification \% | 90.95 | 79.25 | 73.10 | 64.49 | 90.02 | 92.06 | 73.73 | 90.97 | 71.35 |
| Change Point | 102.7549 | 102.5284 | 101.9697 | 101.6194 | 100.1883 | 100.2909 | 100.4583 | 100.5091 | 100.5001 |
| Standard Error | 0.0364 | 0.0339 | 0.0268 | 0.0227 | 0.0068 | 0.0082 | 0.0106 | 0.0111 | 0.0110 |
| Shift Combination | (2,-1,2) | (3,-1,2) | (-3,-1,3) | (-2,-1,3) | (-1,-1,3) | (0,-1,3) | (1,-1,3) | (2,-1,3) | (3,-1,3) |
| Out-of-Control ARL | 3.6584 | 3.1747 | 2.8122 | 3.2938 | 4.3311 | 4.1715 | 4.9215 | 3.2003 | 2.7399 |
| Correct Classification | 92.07 | 90.00 | 94.81 | 90.22 | 62.07 | 92.92 | 60.03 | 91.04 | 94.41 |
| Change Point | 100.4285 | 100.3881 | 99.9770 | 99.9979 | 100.0112 | 100.0401 | 100.0252 | 10.0152 | 100.0026 |
| Standard Error | 0.0101 | 0.0095 | 0.0040 | 0.0044 | 0.0048 | 0.0051 | 0.0049 | 0.0048 | 0.0044 |
| Shift Combination | (-2,1,-3) | (-1,1,-3) | (0,1,-3) | (1,1,-3) | (2,1,-3) | (3,1,-3) | (-3,1,-2) | (-2,1,-2) | (-1,1,-2) |
| Out-of-Control ARL | 3.2482 | 3.8613 | 4.3827 | 4.3073 | 3.2388 | 2.7960 | 3.2044 | 3.7421 | 4.8728 |
| Correct Classification \% | 90.54 | 63.59 | 85.11 | 59.10 | 86.16 | 92.83 | 90.34 | 92.04 | 73.07 |
| Change Point | 100.0594 | 100.1735 | 10.2327 | 100.1871 | 100.1050 | 100.0386 | 100.1935 | 100.3709 | 100.6383 |
| Standard Error | 0.0053 | 0.0067 | 0.0072 | 0.0070 | 0.0060 | 0.0051 | 0.0069 | 0.0092 | 0.0124 |
| Shift Combination | (0,1,-2) | (1,1,-2) | (2,1,-2) | (3,1,-2) | (-3,1,-1) | (-2, 1.-1) | (-1, 1,-1) | (0,1,-1) | (1,1,-1) |
| Out-of-Control ARL | 5.2358 | 5.3319 | 3.7110 | 3.1631 | 4.1101 | 5.1082 | 8.6579 | 11.6192 | 9.5112 |
| Correct Classification \% | 89.56 | 70.19 | 89.35 | 87.48 | 64.67 | 73.82 | 80.22 | 91.77 | 77.25 |
| Change Point | 100.7759 | 100.7505 | 100.5520 | 100.4460 | 100.5374 | 101.0586 | 102.2101 | 103.2265 | 103.1098 |
| Standard Error | 0.0141 | 0.0139 | 0.0118 | 0.0113 | 0.0105 | 0.0165 | 0.0298 | 0.0403 | 0.0404 |
| Shift Combination | (2,1,-1) | (3,1,-1) | (-3,1,0) | (-2,1,0) | (-1,1,0) | $(1,1,0)$ | $(2,1,0)$ | $(3,1,0)$ | (-3,1,1) |
| Out-of-Control ARL | 4.9692 | 3.8664 | 4.3169 | 5.3132 | 12.3960 | 11.4385 | 5.1660 | 4.2320 | 4.2734 |
| Correct Classification \% | 70.39 | 59.48 | 88.70 | 89.51 | 90.18 | 92.81 | 91.03 | 89.30 | 62.55 |
| Change Point | 102.3802 | 102.0469 | 100.7505 | 101.5603 | 104.4455 | 107.5763 | 104.5797 | 103.5209 | 100.5401 |
| Standard Error | 0.0329 | 0.0371 | 0.0126 | 0.0212 | 0.0546 | 0.0889 | 0.0577 | 0.0595 | 0.0106 |
| Shift Combination | (-2,1,1) | (-1,1,1) | $(0,1,1)$ | $(1,1,1)$ | $(2,1,1)$ | $(3,1,1)$ | (-3,1,2) | (-2,1,2) | (-1,1,2) |
| Out-of-Control ARL | 5.2605 | 9.0381 | 12.3460 | 9.2576 | 5.3976 | 4.4596 | 3.2603 | 3.7642 | 5.1685 |
| Correct Classification \% | 73.64 | 83.01 | 90.65 | 79.34 | 73.44 | 63.93 | 89.66 | 91.85 | 73.53 |
| Change Point | 101.0464 | 102.0128 | 102.7313 | 102.5801 | 102.0209 | 101.6733 | 100.1721 | 100.2842 | 100.4450 |
| Standard Error | 0.0168 | 0.0282 | 0.0358 | 0.0341 | 0.0273 | 0.0229 | 0.0066 | 0.0084 | 0.0106 |
| Shift Combination | (0,1,2) | (1,1,2) | $(2,1,2)$ | $(3,1,2)$ | (-3,1,3) | (-2,1,3) | (-1,1,3) | $(0,1,3)$ | $(1,1,3)$ |
| Out-of-Control ARL | 5.3253 | 5.4238 | 3.6517 | 3.1646 | 2.8267 | 3.2936 | 4.3343 | 4.1414 | 4.8536 |
| Correct Classification \% | 91.51 | 71.31 | 91.03 | 89.73 | 95.20 | 90.63 | 61.98 | 92.98 | 61.02 |
| Change Point | 100.5312 | 100.4932 | 100.4525 | 100.3770 | 99.9743 | 99.9908 | 100.0192 | 100.0352 | 100.0235 |
| Standard Error | 0.0116 | 0.0108 | 0.0104 | 0.0096 | 0.0041 | 0.0044 | 0.0048 | 0.0050 | 0.0048 |
| Shift Combination | $(2,1,3)$ | $(3,1,3)$ | (-3,2,-3) | (-2,2,-3) | (-1,2,-3) | (0,2,-3) | (1,2,-3) | $(2,2,-3)$ | (3,2,-3) |
| Out-of-Control ARL | 3.2138 | 2.7403 | 2.7865 | 3.2562 | 3.8521 | 4.4224 | 4.3059 | 3.2550 | 2.7957 |
| Correct Classification \% | 90.64 | 94.41 | 94.92 | 89.92 | 62.62 | 85.75 | 59.06 | 87.27 | 92.87 |
| Change Point | 100.0167 | 100.0053 | 99.9870 | 100.0550 | 100.1709 | 100.2332 | 100.2027 | 100.0994 | 100.0383 |
| Standard Error | 0.0047 | 0.0046 | 0.0042 | 0.0052 | 0.0066 | 0.0074 | 0.0071 | 0.0061 | 0.0052 |
| Shift Combination | (-3,2,-2) | (-2,2,-2) | (-1,2,-2) | (0,2,-2) | (1,2,-2) | (2,2,-2) | (3,2,-2) | (-3,2,-1,) | (-2,2,-1) |
| Out-of-Control ARL | 3.2119 | 3.7385 | 4.9076 | 5.2112 | 5.3378 | 3.7301 | 3.1879 | 4.0737 | 5.1026 |
| Correct Classification \% | 90.54 | 91.97 | 73.1 | 89.80 | 70.41 | 89.36 | 87.54 | 63.80 | 73.7 |
| Change Point | 100.1980 | 100.3580 | 100.6492 | 100.7959 | 100.7544 | 100.5825 | 100.4371 | 100.5565 | 101.0720 |
| Standard Error | 0.0068 | 0.0090 | 0.0124 | 0.0144 | 0.0137 | 0.0120 | 0.0107 | 0.0106 | 0.0168 |
| Shift Combination | (-1,2,-1) | (0,2,-1) | (1,2,-1) | (2,2,-1) | (3,2,-1) | (-3,2,0) | (-2,2,0) | (-1,2,0) | $(1,2,0)$ |
| Out-of-Control ARL | 8.5634 | 11.6575 | 9.5186 | 5.0006 | 3.8882 | 4.2910 | 5.3134 | 12.4540 | 11.4138 |
| Correct Classification \% | 80.00 | 91.64 | 78.61 | 71.01 | 59.77 | 88.70 | 90.95 | 90.70 | 92.17 |
| Change Point | 102.2600 | 103.2664 | 103.1395 | 102.3949 | 101.9942 | 100.7501 | 101.5931 | 104.4138 | 107.5986 |
| Standard Error | 0.0300 | 0.0413 | 0.0401 | 0.0333 | 0.0363 | 0.0123 | 0.0215 | 0.0545 | 0.0881 |
| Shift Combination | $(2,2,0)$ | $(3,2,0)$ | (-3,2,1) | (-2,2,1) | (-1,2,1) | $(0,2,1)$ | $(1,2,1)$ | $(2,2,1)$ | $(3,2,1)$ |
| Out-of-Control ARL | 5.2078 | 4.2245 | 4.2959 | 5.2223 | 9.0037 | 12.2175 | 9.2177 | 5.3535 | 4.4140 |
| Correct Classification \% | 91.23 | 89.46 | 63.81 | 73.68 | 82.63 | 91.22 | 78.99 | 73.01 | 63.56 |
| Change Point | 104.5731 | 103.6618 | 100.5525 | 101.0294 | 102.0193 | 102.7048 | 102.5810 | 102.0341 | 101.6662 |
| Standard Error | 0.0572 | 0.0632 | 0.0105 | 0.0164 | 0.0282 | 0.0356 | 0.0345 | 0.0273 | 0.0228 |
| Shift Combination | (-3,2,2) | (-2,2,2) | (-1,2,2) | $(0,2,2)$ | $(1,2,2)$ | $(2,2,2)$ | $(3,2,2)$ | (-3,2,3) | ((-2,2,3) |
| Out-of-Control ARL | 3.2618 | 3.7624 | 5.1528 | 5.3041 | 5.4895 | 3.6669 | 3.1553 | 2.8286 | 3.2971 |
| Correct Classification \% | 90.02 | 92.51 | 74.11 | 91.59 | 71.6 | 92.09 | 89.54 | 94.93 | 90.35 |
| Change Point | 100.1966 | 100.2828 | 1004461 | 100.5077 | 100.5027 | 100.4529 | 100.3984 | 99.9698 | 99,9924 |
| Standard Error | 0.0068 | 0.0083 | 0.0103 | 0.0110 | 0.0110 | 0.0103 | 0.0096 | 0.0040 | 0.0044 |
| Shift Combination | $(-1,2,3)$ | $(0,2,3)$ | $(1,2,3)$ | $(2,2,3)$ | $(3,2,3)$ | (-3,3,-3) | (-2,3,-3) | (-1,3,-3) | (0,3,-3) |
| Out-of-Control ARL | 4.3046 | 4.1805 | 4.8674 | 3.2182 | 2.7663 | 2.7919 | 3.2445 | 3.8507 | 4.4214 |
| Correct Classification | 61.38 | 92.69 | 59.88 | 91.01 | 95.08 | 94.99 | 89.89 | 62.67 | 85.23 |
| Change Point | 100.0183 | 100.0200 | 100.0234 | 100.0127 | 100.0026 | 99.9849 | 100.0659 | 100.1764 | 100.2278 |
| Standard Error | 0.0047 | 0.0049 | 0.0049 | 0.0048 | 0.0047 | 0.0043 | 0.0053 | 0.0067 | 0.0073 |
| Shift Combination | (1,3,-3) | (2,3,-3) | (3,3,-3) | (-3,3,-2) | (-2,3,-2) | (-1,3,-2) | (0,3,-2) | (1,3,-2) | (2,3,-2) |
| Out-of-Control ARL | 4.3127 | 3.2452 | 2.7687 | 3.1086 | 3.7395 | 4.8999 | 5.2439 | 5.2697 | 3.7195 |


| Correct Classification \% | 58.30 | 86.80 | 92.35 | 90.70 | 91.83 | 72.81 | 89.25 | 69.74 | 89.46 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Change Point | 100.1914 | 100.1049 | 100.0271 | 100.1996 | 100.3589 | 100.6305 | 100.7811 | 100.7604 | 100.6040 |
| Standard Error | 0.0070 | 0.0061 | 0.0051 | 0.0069 | 0.0092 | 0.0122 | 0.0139 | 0.0139 | 0.0122 |
| Shift Combination | $(3,3,-2)$ | $(-3,3,-1)$ | $(-2,3,-1)$ | $(-1,3,-1)$ | $(0,3,-1)$ | $(1,3,-1)$ | $(2,3,-1)$ | $(3,3,-1)$ | $(-3,3,0)$ |
| Out-of-Control ARL | 3.1791 | 4.1293 | 5.1030 | 8.5891 | 11.7086 | 9.5472 | 4.9842 | 3.8922 | 4.2817 |
| Correct Classification \% | 87.60 | 65.28 | 74.41 | 80.40 | 91.88 | 77.56 | 70.48 | 59.36 | 88.82 |
| Change Point | 100.4555 | 100.5546 | 101.0987 | 102.2632 | 103.2990 | 103.1824 | 102.3946 | 102.0207 | 100.7718 |
| Standard Error | 0.0107 | 0.0106 | 0.0167 | 0.0304 | 0.0409 | 0.0410 | 0.0335 | 0.0351 | 0.0127 |
| Shift Combination | $(-2,3,0)$ | $(-1,3,0)$ | $(1,3,0)$ | $(2,3,0)$ | $(3,3,0)$ | $(-3,3,1)$ | $(-2,3,1)$ | $(-1,3,1)$ | $(0,3,3)$ |
| Out-of-Control ARL | 5.3276 | 12.2106 | 11.4751 | 5.1728 | 4.2090 | 4.2929 | 5.1941 | 8.9355 | 12.0587 |
| Correct Classification \% | 90.01 | 90.96 | 92.64 | 91.56 | 89.76 | 63.68 | 73.63 | 82.59 | 91.17 |
| Change Point | 101.6087 | 104.3907 | 107.5159 | 104.5898 | 103.4984 | 100.5474 | 101.0108 | 102.0734 | 102.6929 |
| Standard Error | 0.0214 | 0.0542 | 0.0881 | 0.0575 | 0.0614 | 0.0106 | 0.0159 | 0.0288 | 0.0351 |
| Shift Combination | $(1,3,1)$ | $(2,3,1)$ | $(3,3,1)$ | $(-3,3,2)$ | $(-2,3,2)$ | $(-1,3,2)$ | $(0,3,2)$ | $(1,3,2)$ | $(2,3,2)$ |
| Out-of-Control ARL | 9.2506 | 5.3887 | 4.3996 | 3.2424 | 3.7790 | 5.1532 | 5.2658 | 5.3745 | 3.6578 |
| Correct Classification \% | 79.53 | 72.81 | 63.55 | 90.51 | 92.17 | 73.75 | 91.71 | 71.56 | 91.91 |
| Change Point | 102.5587 | 102.0309 | 101.6013 | 100.1776 | 100.2810 | 100.4357 | 100.5141 | 100.5098 | 100.4502 |
| Standard Error | 0.0338 | 0.0271 | 0.0222 | 0.0067 | 0.0084 | 0.0105 | 0.0113 | 0.0112 | 0.0103 |
| Shift Combination | $(3,3,2)$ | $(-3,3,3)$ | $(-2,3,3)$ | $(-1,3,3)$ | $(0,3,3)$ | $(1,3,3)$ | $(2,3,3)$ | $(3,3,3)$ |  |
| Out-of-Control ARL | 3.1823 | 2.8212 | 3.2982 | 4.2904 | 4.1435 | 4.8685 | 3.2056 | 2.7630 |  |
| Correct Classification \% | 90.15 | 94.93 | 90.60 | 60.88 | 93.49 | 59.68 | 91.09 | 94.73 |  |
| Change Point | 100.3983 | 99.9688 | 99.9777 | 100.0100 | 100.0273 | 100.0205 | 100.0261 | 99.9989 |  |
| Standard Error | 0.0097 | 0.0040 | 0.0045 | 0.0047 | 0.0049 | 0.0050 | 0.0048 | 0.0046 |  |

## IV. Conclusions

When a process involved multi related quality characteristics is controlled statistically, an out-of-control signal itself could not lead the practitioners to an effective root-cause analysis. In this case a multi task scheme which is able to estimate the change point and simultaneously performs effectively a diagnostic analysis to identify the quality characteristic contributing to the out-of-control condition is required. In this paper a multi task scheme based on supervised learning was proposed which could help practitioners not only detect an out-of-control condition, but also the scheme helps to identify the change point and diagnose the variable(s) responsible to the new condition, all at the same time. Performance of the multi task scheme was evaluated via 287 scenarios of mean step change and the results indicated the high capabilities of the model.

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