

Lightweight Mirrors for Space X-Ray Telescopes

M. Mika, L. Pina, M. Landova, L. Sveda, R. Havlikova, V. Marsikova, R. Hudec, and A. Inneman

Abstract—Future astronomical projects on large space x-ray imaging telescopes require novel substrates and technologies for the construction of their reflecting mirrors. The mirrors must be lightweight and precisely shaped to achieve large collecting area with high angular resolution. The new materials and technologies must be cost-effective. Currently, the most promising materials are glass or silicon foils. We focused on precise shaping these foils by thermal forming process. We studied free and forced slumping in the temperature region of hot plastic deformation and compared the shapes obtained by the different slumping processes. We measured the shapes and the surface quality of the foils. In the experiments, we varied both heat-treatment temperature and time following our experiment design. The obtained data and relations we can use for modeling and optimizing the thermal forming procedure.

Keywords—Glass, silicon, thermal forming, x-ray

I. INTRODUCTION

FOR the last three decades of x-ray astronomy, observations delivered by imaging x-ray telescopes have significantly contributed to important discoveries of current astrophysics [1-5]. Nowadays, there are new projects on high-resolution imaging telescopes with large collecting areas that require lightweight optics allowing multiple nesting with angular resolution below 5 arcsec. The officials of ESA/NASA/JAXA collaborative space project on the International X-Ray Observatory (IXO) have given preferences to cost-effective materials and technologies for the construction of the mirrors [6]. Currently, the most promising materials are thin glass or Si foils that are commercially available with very low micro-roughness [7-13]. We focused on the development and optimization of thermal forming technology with the aim of precise shaping the foils that they can fit the mostly used Wolter-I geometry [14] while keeping their surface micro-roughness sufficiently low [15-17]. To satisfy the demanding construction parameters, we must precisely control the forming process, which requires the deep understanding of relations between thermal forming conditions and the parameters of the produced optical components for x-ray reflecting mirrors.

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M. Mika is with the Institute of Chemical Technology, Technicka 5, Prague 6, 166 28, Czech Republic (phone: +420 220 444 102; fax: +420 220 350; e-mail: martin.mika@vscht.cz).

L. Pina is with the Czech Technical University in Prague, Brehova 7, Prague 1, 115 19, Czech Republic (e-mail: ladislav.pina@fjfi.cvut.cz).

M. Landova is with the Institute of Chemical Technology, Technicka 5, Prague 6, 166 28, Czech Republic (phone: +420 220 444 102; fax: +420 220 350; e-mail: martina.landova@vscht.cz).

II. EXPERIMENTAL

A. Free slumping of glass

In our forming experiments, we used commercial borosilicate glass Desag D263 that is produced by Schott company [18]. The glass is produced with a very low micro-roughness of only few 0.1 nm. It exhibited a high chemical durability, and its density was $2.51 \text{ g}\cdot\text{cm}^{-3}$. We thermally formed thin glass foils of rectangular shape $75\times 25\times 0.75 \text{ mm}$.

Before the forming experiment, we placed a glass foil on a supporting mandrel with concave surface of radius $r = 122.3 \text{ mm}$, as it is illustrated in Figure 1. For the mandrel, we developed a special composite material which prevents sticking of the foil to the mandrel at high temperatures. Then, the foil was heated in an electric furnace from the room temperature up to temperatures slightly above the glass transition temperature $T_g = 557^\circ\text{C}$. At these constant temperatures the foil was sagging under its own weight. When we are above T_g , we can form the glass foils by plastic deformation without forming residual mechanical stresses. For the heat treatment, we followed our experiment design and

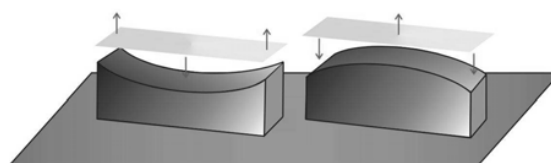


Fig. 1 Concave and convex mandrels for glass forming

varied the heat-treatment temperature T from 600 to 660°C , and the heat-treatment time t from 60 to 90 min. Corresponding glass viscosities η were from $10^{11.2}$ to $10^{9.3} \text{ dPa}\cdot\text{s}$. After the heat treatment, the foil was slowly cooled down to avoid the formation of residual mechanical stresses.

B. Forced slumping of glass

For our forced glass slumping experiments, we used the same experimental set up like for the free slumping. In addition, during the heat treatment, we applied vertical force of 0.6 N by placing a convex mandrel on the top surface of a glass foil. In this case, T varied from 600 to 650°C , η was from $10^{11.2}$ to $10^{9.6} \text{ dPa}\cdot\text{s}$, and t was from 15 to 60 min.

C. Thermal forming of silicon

For shaping experiments with silicon, we selected 0.6 mm thin monocrystal wafers with the orientation $\langle 100 \rangle$. They were doped with B and their electric resistance was in the range of 3-25 Ω . Their density was $2.33 \text{ g}\cdot\text{cm}^{-3}$. From the wafers, we cut rectangular samples 75×25 or $50\times 50 \text{ mm}$. In our approach, we shaped the silicon foils by hot plastic deformation [19-21]. We placed a silicon foil on a frame

consisting of two parallel corundum rods supporting the foil at the edges. Then, we heated the foil above 1000°C, to the region of plastic deformation. The forming process was relatively slow; therefore, we had to apply additional vertical force in the range of 1-5 N using a cylindrical or a spherical mandrel placed on the top of the silicon foil. To achieve sufficient bending, we kept the foil at high temperature for 60 to 120 min.

D. Metrology

Shapes of the thermally formed samples were measured with a Taylor Hobson PGI PLUS contact profilometer. For each sample, we measured three parallel lines of orthogonal directions; in the center and close to the edges. Recorded data were processed with Taylor Hobson and Matlab software. Using the profilometer, we also determined surface waviness and micro-roughness of our samples. The surface micro-roughness was also measured with the optical interferometry (ZYGO) and the Atomic Force Microscopy (AFM).

III. RESULTS

By the heat treatment at temperatures above T_g , we successfully shaped the glass foils by free slumping; an example of the shaped glass foil is shown in Figure 2. The

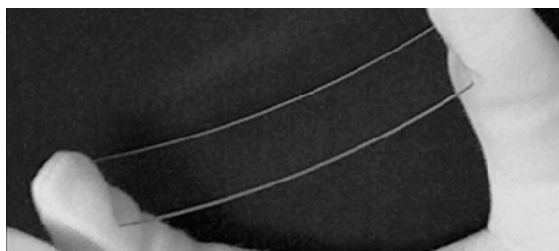


Fig. 2 Glass foil formed by free slumping

obtained shapes were close to parabola, but it was also possible to fit them by circle with peak-to-valley values typically between 10 to 35 μm . For the free slumping of glass foils, the shape was dependent on heat-treatment conditions. To illustrate these effects, we calculated a 3-D plot and a map in Figures 3 and 4 illustrating the effect of T and t on the shape radius of glass foils formed by free slumping.

For the forced slumping of glass foils, the shape was mostly close to the shape of the mandrel with $r = 122.3$ mm. In this case, we calculated differences between the radius of the foil and the mandrel. The following 3-D plot and a map in Figures 5 and 6 show how this difference depended on T and t . The surface micro-roughness of the glass foils was also influenced by forming conditions. The effect of both T and t on the micro-roughness R_a , measured with the profilometer, you can see in Figures 7 and 8. The micro-roughness R_a measured with ZYGO or AFM was around 0.3 nm. The surface of the foils shaped by the free slumping, measured with the mechanical profilometer, had R_a also about 0.3 nm.

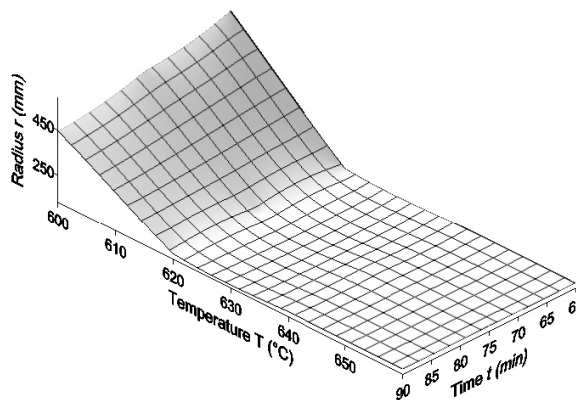


Fig. 3 Radius of glass foil shape as a function of temperature and time formed by the free slumping

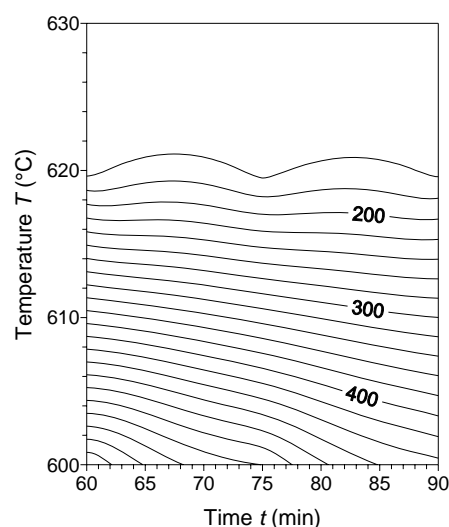


Fig. 4 Radius isolines of glass foil shape as a function of temperature and time formed by the free slumping

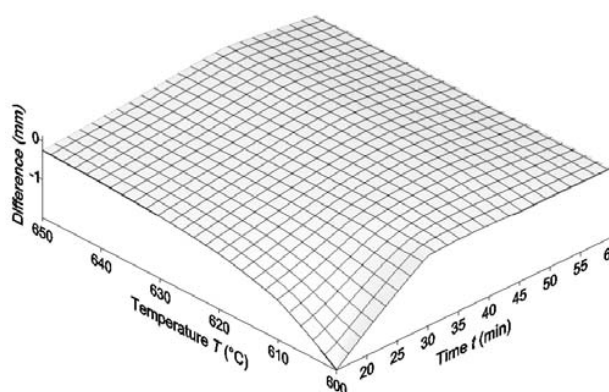


Fig. 5 Shape radius difference between a glass foil and the mandrel as a function of temperature and time for forced slumping

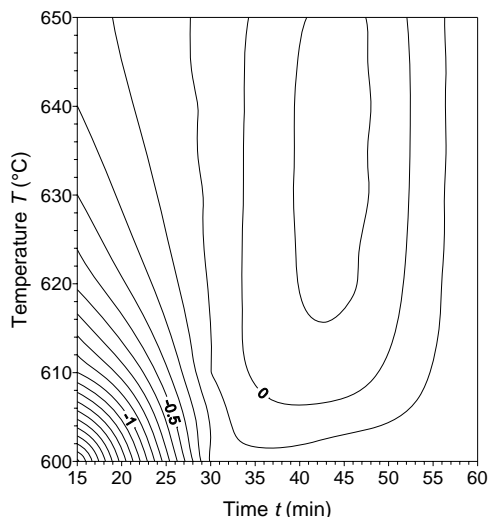


Fig. 6 Isolines of shape radius difference between a glass foil and the mandrel as a function of temperature and time for forced slumping

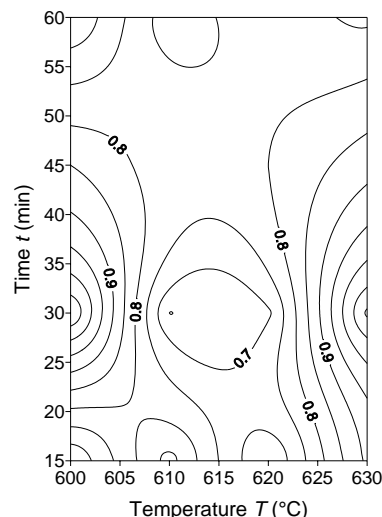


Fig. 8 Isolines of constant surface micro-roughness, measured with mechanical profilometer, of glass foils formed by forced slumping as a function of temperature and time

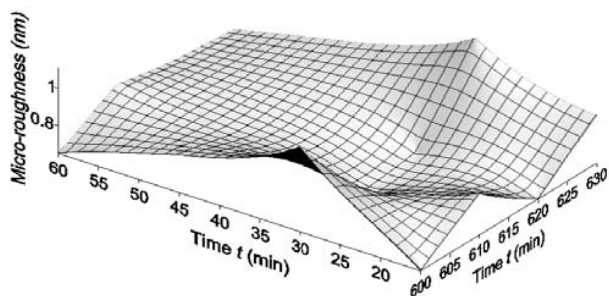


Fig. 7 Surface micro-roughness, measured with mechanical profilometer, of glass foils formed by forced slumping as a function of temperature and time

We successfully shaped the silicon foils by hot plastic deformation, and thus, confirmed again the feasibility of this process. We used cylindrical pressing mandrels with radius from 10 to 75 mm as well as spherical mandrels of radius 30 mm. By changing heat-treatment conditions and the geometry of a pressing mandrel, we were able to form silicon foils with various curvatures; for example, the foils with radius 252 and 795 mm are shown in Figures 9 and 10.

IV. DISCUSSION

In the forming experiments, we compared the shapes of glass foils formed by free or forced slumping. The obtained shapes were close to parabola but it was also possible to fit them with circle with reasonably low deviations characterized by peak-to-valley values below 36 μm . However, we still continue in our effort to decrease these values to the micrometer region by optimizing the forming process. By this



Fig. 9 Si foil of radius 252 mm shaped by hot plastic deformation



Fig. 10 Si foil of radius 398 mm shaped by hot plastic deformation

approach, we could use the radius as just one parameter to characterize the shape. For free slumping, we observed that at temperatures above roughly 620°C, i.e., at $\eta = 10^{10.5}$ dPa·s, the glass foil's shape did not significantly change with T and t . The sagging velocity was high enough for the foil to reach the top surface of the mandrel and rest on it. The foils' radii were in the range of 130-150 mm, that is a little bit higher than the mandrel's radius $r = 122.3$ mm, indicating more open shape. On the other hand, below 620°C, the shape was strongly dependent on T and also quite significantly dependent on t . At these temperatures, the sagging glass foil did not reach the mandrel surface and the resulting shape was much more open with radii spanning from 150 to 590 mm. For forced slumping, we put a pressing mandrel on the top surface of the glass foil, which significantly speeded up the sagging. The glass foils almost always reached the mandrel's surface. Thus, the foils' radius was found to be very close to the radius of the mandrel. The map with the differences contains a zero isoline that marks the temperature-time area where we can obtain the

radius of the foil to be the same as, of the mandrel. Only in a small area below 620°C and t shorter than 30 min, the radius was steeply decreasing with the decreasing T and t . Our measurements with the profilometer revealed that the micro-roughness of glass foils' surfaces was strongly dependent on T and t when the foils were formed by the forced slumping. The 3-D plot and the corresponding map indicate the temperature-time area where we achieved the R_a values to be below 0.7 nm. This area is approximately between 610 and 620°C with t between 25 and 35 min. The upper pressing mandrel could probably significantly affect the foil's surface quality when the forming conditions are not optimal. The measurements of the foils' surface using ZYGO and AFM determined R_a to be much lower, only 0.3 nm. The data obtained from the profilometer were probably affected by the waviness of the samples. For the free slumping, the measurements with profilometer determined the R_a values to be about 0.3 nm. It is probable that the untouched surface of these glass foils had significantly better smoothness.

During the forming experiments, we proved that the composite mandrel is suitable for the thermal forming of glass foils for the mirrors of x-ray space telescopes. The composite material prevents sticking of glass to the mandrel at high temperatures, and the manufacture of the mandrel is simple and cost-effective.

By controlling T and t in a particular temperature-time area, we could also prepare foils with various radii, and hence, use just one mandrel for manufacturing different mirror reflectors. This approach could also significantly lower the production cost of x-ray telescopes mirrors.

In our experiments, we confirmed that thin silicon foils can be effectively shaped by thermal forming process. However, the process is complex, and to successfully shape the foils, we need to use wafers with sufficient concentration of dislocations with proper orientation. To achieve sufficient bending, we had to heat up the foils above 1000°C, to the region of plastic deformation, where the dislocations move in a viscous manner, and keep them at high temperature for more than 60 min. By using the pressing mandrels of different geometry; for example cylinders or spheres of various radii, and by controlling heat-treatment conditions, we could form the foils to required shapes. However, the precise shaping of the foils at such high temperatures turned to be a highly demanding process.

V. CONCLUSION

We compared the shapes of glass foils thermally formed by free or forced slumping in our composite mandrel. The obtained shapes were fitted with circle. The free slumping process formed shapes with bigger radii than the radius of the mandrel. At temperatures below 620°C, the radius strongly increased with the decreasing temperature and time of heat-treatment. The forced slumping formed shapes with radii very close to the mandrel. We defined the time-temperature area where these radii are the same. The samples formed by the free slumping had lower micro-roughness than those formed by the

forced slumping.

By controlling T and t in a particular temperature-time area, we could also prepare foils with various radii and sufficiently low micro-roughness, and hence, use just one mandrel for manufacturing different mirror reflectors. This approach could also significantly lower the production cost of x-ray telescopes mirrors.

Thin silicon foils could be effectively shaped by force in the region of hot plastic deformation if they contain the sufficient concentration of properly oriented dislocations. To facilitate the movement of dislocations, the foils had to be heated above 1000°C for longer than 60 min. However, the precise shaping of silicon at high temperatures turned to be a highly demanding process. Nevertheless, we still consider the silicon optics to be a very promising technology for lightweight and high-resolution x-ray imaging telescopes.

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Martin Mika was born in Prague, Czech Republic, on October 30, 1964. He graduated at the Institute of Chemical Technology Prague (ICT) in "Chemistry and technology of glass" in 1988. In 1995, he obtained PhD in "Chemistry and technology of inorganic materials" at the same institute. He had been a visiting scientist at the Pacific Northwest National Laboratory, Richland, Washington from 1996 to 1997. Since 1998 he occupies a position of assistant professor at the Department of Glass and Ceramics, ICT. His research and teaching activities are glass materials – influence of chemical composition on their physical and chemical properties, ion migration, experimental design, calculation and modeling of their properties, formulation and preparation of special glasses (for example, optical glass for integrated optics, high level waste glass, or organic-inorganic hybrid glass). In 2004, he was awarded NATO Senior Fellowship and spent two months as a visiting scientist in the Institute of Applied Physics in Florence, Italy. Dr. Mika received Professor Vittorio Gottardi Memorial Prize granted by the International Commission on Glass for outstanding individual accomplishment in the field of glass in 2003. He is a member of the Czech Glass Society and the International Commission on Glass technical commission TC10 "Optical properties of glass".