

A Review: Comparative Analysis of Arduino Micro Controllers in Robotic Car

C. Rajan, B. Megala, A. Nandhini, C. Rasi Priya

Abstract—Robotics brings together several very different engineering areas and skills. There are various types of robot such as humanoid robot, mobile robots, remotely operated vehicles, modern autonomous robots etc. This survey paper advocates the operation of a robotic car (remotely operated vehicle) that is controlled by a mobile phone (communicate on a large scale over a large distance even from different cities). The person makes a call to the mobile phone placed in the car. In the case of a call, if any one of the button is pressed, a tone equivalent to the button pressed is heard at the other end of the call. This tone is known as DTMF (Dual Tone Multiple Frequency). The car recognizes this DTMF tone with the help of the phone stacked in the car. The received tone is processed by the Arduino microcontroller. The microcontroller is programmed to acquire a decision for any given input and outputs its decision to motor drivers in order to drive the motors in the forward direction or backward direction or left or right direction. The mobile phone that makes a call to cell phone stacked in the car act as a remote

Keywords—Arduino Micro-controller, Arduino UNO, DTMF, Mobile phone, Robotic car.

I. INTRODUCTION

A. Robot

FOR many people robot is a machine that imitates a human—like androids in Star Wars, Star Trek and Terminator. However much of these robots incarcerate our thoughts, such robots still only dwell in science fiction. Still, it is impossible to give a robot enough 'common sense' to reliably interact with a dynamic world.

Today, robotics is a rapidly growing field in researching, designing, and building new robots practical purpose, whether domestically, commercially, or militarily. Many robots help humans by doing jobs such as defusing bombs, mines and exploring shipwrecks.

B. Types of Robots by Application

- Industrial robots are robots used in an industrial manufacturing environment. Generally these are articulated arms specifically developed for applications such as material handling, painting, welding and others. If we judge this by an application, it also includes some automated guided vehicles and other robots.
- Domestic or household robots are used at home. This type of robots includes several quite different devices such as

robotic pool cleaners, robotic vacuum cleaners, gutter cleaners, sweepers and other robots that can do different chores. And also some surveillance and telepresence robots could be regarded as household robots if used in that environment.

- Medical robots are used in medicine and medical institutions. And also in some automated guided vehicles and lifting aides.
- Service robots are the robots that don't fall into other types by usage. These might be robots used for research, different data gathering robots, etc.
- Military robots are used in military. This kind of robots includes different transportation robots, bomb disposal robots and reconnaissance drones. Robots initially created for military purposes can be used in search and rescue, law enforcement, and other related fields.
- Entertainment robots are robots used for entertainment. It is a very broad category. It begins with toy robots such as robosapien or the running alarm clock and ends with real heavyweights such as articulated robot arms used as motion simulators.
- Space robots include robots used on the International Space Station, Canadarm which was used in Shuttles, as well as Mars rovers and other robots used in space.
- Hobby and competition robots are that you create. Sumobots, line followers, robots made just for fun and robots made for competition [15].

C. Robotic Vehicle and DTMF Technology

A remote control vehicle (RCV) is defined as any mobile device that is controlled by a means that does not restrict its motion with an origin external to a device. This is commonly a radio control device, infrared controller or a cable between control and vehicle. A RCV is at all times controlled by a human and takes no positive action autonomously [2]. Mostly wireless-controlled robots use RF circuits, which have the drawbacks of limited frequency, limited control and limited frequency range. Since here cell phone is used to control the operation of the robot, it can overcome these limitations. The cell phone signal has a wide range over the surface that's why robot can be operated from far away without disturbance and interference with other signals. The control action of robot includes three parts Perception, Processing and Action. Generally, the preceptors are the sensors mounted on the robot, processing can be done by the on-board microcontroller or processor, and then the action is performed using motors [26].

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D. History of DTMF

Before DTMF was created, telephone networks used a dialing system called Decadic (also known as Pulse Dial). The Decadic system was used widely in modern telephone networks to dial numbers which could be entered by the telephone companies' users. The Decadic (Pulse Dialing) system used a series of clicks (which could be heard through the speaker of the phone) to dial the numbers which were dialed via a keypad or rotary dial. The clicking sounds were the connection of the phone line being connected, disconnected and reconnected over again in a certain pattern. The Decadic (Pulse Dialing) system was very useful, but limited to the local exchange connections, demanding an operator to connect long distance calls. In late years of 1950, DTMF was being developed at Bell Labs for the purpose of allowing tone signals to dial long distance numbers, which could be potentially be dialed not only via standard wire networks, but also through radio links and or satellites [1].

E. DTMF Technology

DTMF stands for Dual Tone Multiple Frequency. DTMF is a term which is used in the telephone industry. DTMF generation is a composite audio signal of two tones between the frequency of 697Hz and 1633Hz. The DTMF keypad is arranged in such a way that each row will have its own unique tone frequency and also each column will have its own unique tone. Fig.1 is a representation of the typical DTMF keypad and the associated row/column frequencies. When any of the keys like "1", "2", "*", "#", etc., is pressed, exact code is transmitted. This code consists of two frequencies among which first one is a higher frequency and the second one is a lower frequency as shown in Fig. 1 [3], [20]. The engineers had envisioned phones being used to access computers, and surveyed the number of companies to see what they would need for this task. This led to the addition of the number sign (#, sometimes called 'octothorpe' in this context) and the asterisk or "star" (*) keys as well as a group of keys for menu selection: A, B, C and D. The levels of priority available were Flash Override (A), Flash (B), Immediate (C), and Priority (D), with Flash Override being the highest priority [19].

Mobile keypad (as represented in Fig. 2) is laid out in a 4x4 framework, although the original DTMF keypad had an additional column for four menu selector keys. When used to dial a phone number, pressing a single key will produce a pitch consisting of two simultaneous pure tone sinusoidal frequencies. The row in which the key appears decides the lower frequency and the column determines the higher frequency. For example, pressing a key will result in a sound

composed of both 697 Hz and 1209 Hz tone. The original keypads had levers within, so each button can activate two contacts. The multiple tones are the cause for calling the system with multiple frequencies. These multiple tones are then decoded by the switching center to determine which key was pressed [6], [5].

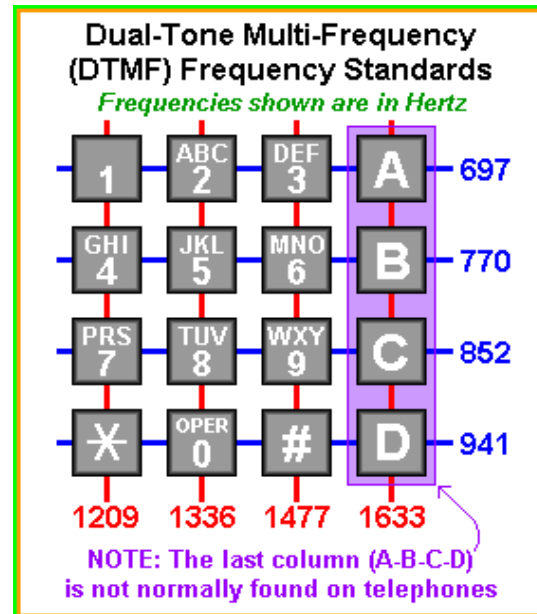


Fig. 1 Dual-Tone Multi-Frequency (DTMF) Frequency Standards



Fig. 2 Mobile keypad

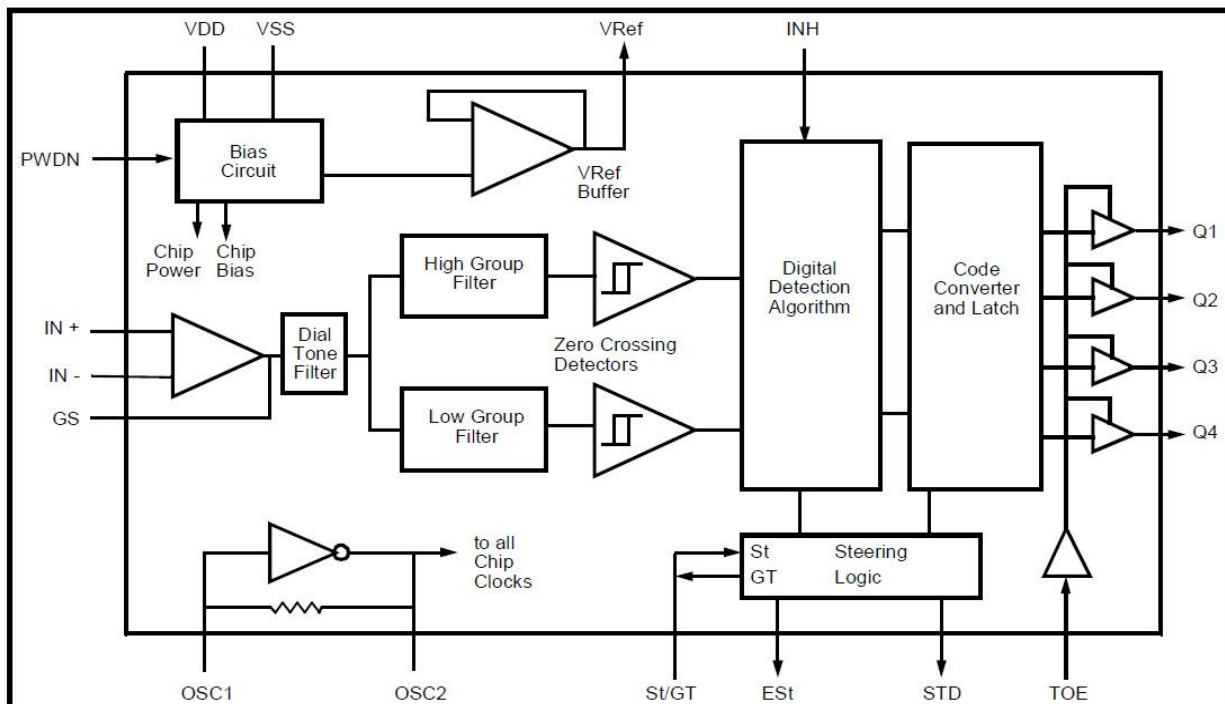


Fig. 3 MT8870D

The 12 keys on a cell phone (0, 1... 8, 9, *, #) has unique signal associated with itself. This signal is called DTMF signal. While the call is on, the pressing of any numerical key leads to generation of DTMF signal which is audible on the other side. It is also possible to record DTMF tones using a tape recorder or computer microphone, which then played into the mouthpiece of your telephone to dial numbers. Though if there is a significant amount of background sound behind the recorded DTMF tones, the tones may not work correctly and cause problems when trying to dial numbers. You can also download DTMF tones through the S.C.P website in WAV or MP3 format [17].

F. Earphone Jack

There are two ways of taking output from mobile phone.

- Output can be taken from speaker (which is nearer to your ear while calling) and by using microphone it converts sound waves into electrical signals. (It is a tedious process).
- The other way is through earphone jack (3.5 MM).



Fig. 4 Earphone jack



Fig. 5 Phone connectors

Earphone jack is also termed as an audio jack, phone jack, phone plug and jack plug. In electronics, a phone connector is a common family of connector typically used for analog signals, mainly audio. It is cylindrical in shape, normally with two, three or four contacts. Three-contact versions are called as TRS connectors, where T stands for "tip", R stands for "ring" and S stands for "sleeve". Similarly, two- and four-contact versions are called TS and TRRS connectors respectively.

The "mini" connector has a diameter of 3.5 mm (approx. 1/8 inch) and the "sub-mini" connector has a diameter of 2.5 mm (approx. 3/32 inch). Four- and five-conductor versions of 3.5 mm plug are used for certain applications. A four-conductor version is frequently used in compact camcorders, portable media players and also in laptop computers and smartphones,

providing stereo sound plus video signals. Proprietary interfaces using both four- and five-conductor versions exist, where extra conductors are used to supply power for accessories. When a three-conductor version of the 6.35 mm (1/4 in) jack was introduced for use with stereo headphones, which was given a sharper tip profile in order to make it possible to manufacture jacks (sockets) that would accept only stereo plugs, in order to avoid short-circuiting the right channel of the amplifier.

- 2.5 mm mono (TS)
- 3.5 mm mono (TS)
- 3.5 mm stereo (TRS)
- 6.35 mm (1/4 in) (TRS)

TT: The professional audio field and the telecommunication industry use tiny telephone (TT) connectors in patch bays. TT connectors are used for professional console and outboard patchbays in studio and live sound applications, where there are large numbers of patch points are needed in a limited space.

TRS: The three-conductor (TRS) versions are capable of handling balanced line signals and are used in professional audio installations.

II. RELATED WORKS

Sabuj Das Gupt et al. [2013] delivered that the operation of a toy car that is controlled by a mobile phone, makes a call to the mobile phone stacked in the car. In the course of a call, if any button is pressed, a tone equivalent to the button pressed is heard at the other end of the call. This tone is called DTMF (dual-tone- multiple- frequency). The car recognizes this DTMF tone with the help of the phone stacked in the car. The received tone is processed by the (ATmega16) microcontroller with the help of DTMF decoder MT8870. The DTMF tone is decoded into its equivalent binary digit by the decoder and this binary number is sent to the microcontroller. The microcontroller is programmed to acquire a decision for any given input and outputs its decision to motor drivers in order to drive the motors in the forward direction or backward direction or left and right direction. The mobile phone that makes a call to cell phone stacked in the car act as a remote. For this reason this paper does not require construction of receiver and transmitter units [23].

Awab Fakih et al. say conservatively, wireless-controlled robots use RF circuits, which have the limitations of working range, frequency range and control. Use of a mobile phone for robotic control can overcome these limitations. It provides the advantages of large coverage area, robust control, no interference with other controllers and up to twelve controls. Although the appearance and capability of robots vary vastly, all the robots share the features of the mechanical, movable structure under some form of control. The control of robots involves three distinct phases such as Perception, Processing and Action. Generally, preceptors are the sensors mounted on the robot, processing can be done by the on-board microcontroller or processor, and the task (action) is performed using motors or with some other actuators [2].

III. ARDUINO MICROCONTROLLER

A. History

Arduino started in 2005 as a project for students at the Interaction Design Institute Ivrea in Ivrea, Italy. By that time, program students used a "BASIC Stamp" at a cost of \$100, which is considered expensive for students [4]. The name "Arduino" comes from a bar in Ivrea, where few of the founders of the project used to meet. The bar itself was called after Arduino, Margrave of Ivrea from 1002 to 1014 [18].

A hardware thesis was contributed for a wiring design by Colombian student Hernando Barragan. After the Wiring [22] platform was complete, researchers worked to make it easier, low cost and available to the open source community. The school finally closed, but the researchers, including David Cuartielles, advanced the idea [4].

Arduino is an open - source single board microcontroller, intended to formulate a process of exploiting electronics in multidisciplinary projects more accessible [25].

There are three broad ways to differentiate the various Arduino boards.

- processing capabilities
- feature set
- form fact

Processing capabilities are the microcontroller's memory, clock speed and bandwidth. The processing hardware is entirely determined by which microcontroller chip, the board utilizes, and constrains what kinds of software can run on that board.

Feature set includes all the stuff on the board other than the microcontroller, such as input and output pins, built-in hardware like buttons and LEDs and the interfaces available on the board (USB, Ethernet, etc.).

Form factor: Arduino is meant to be built into physical projects in which form factor is necessary. Arduino comes with a variety of shapes and sizes.

B. Hardware

An Arduino board consists of an Atmel 8-bit AVR microcontroller with complementary components that facilitate programming and incorporation into other circuits. And an important aspect of the Arduino is its standard connectors, which means users connect the CPU board to a variety of interchangeable add-on modules called as shields. Some shields communicate with the Arduino board directly over various pins, but most of the shields are individually addressable via an I²C serial bus—so many shields can be stacked and used in parallel alignment. Official Arduinos have used the megaAVR series of chips, which is ATmega8, ATmega168, ATmega328, ATmega1280, and ATmega2560. A hand ful of other processors have been used by Arduino compatibles. Most boards have include a 5 volt linear regulator and a 16 MHz crystal oscillator (or ceramic resonator in some variants), although some designs like the LilyPad run at 8 MHz and dispense with the onboard voltage regulator due to specific form-factor restrictions. An Arduino microcontroller is also programmed with a boot loader that simplifies uploading of

programs to the on-chip flash memory and compared with other devices that typically need an external programmer, which makes using an Arduino more straightforward by allowing the use of an ordinary computer as the programmer.

At a conceptual level, when using the Arduino software stack, all boards are programmed through an RS-232 serial connection, but the way which is implemented varies by hardware version. Serial Arduino boards contain a special circuit called level shifter circuit to convert between RS-232-level and TTL-level signals. The ongoing Arduino boards are programmed through USB, implemented using USB-to-serial adapter chips such as the FTDI FT232. Some alternatives such as the Arduino Mini and the unofficial Arduino, use a detachable USB-to-serial adapter board or cables, Bluetooth or other methods. (When used with traditional microcontroller tools instead of the Arduino IDE, standard AVR ISP program is used.)

The Arduino board exposes most of the microcontroller's I/O pins for use by variant circuits. The Diecimila, Duemilanove, and current Uno provide 14 digital I/O pins, six of fourteen which can produce pulse-width modulated signals, and six analog inputs, this can also be used as six digital I/O pins. These pins are on the top of the board, via female 0.10-inch (2.5 mm) headers. Several plug-in applications shields are also commercially obtainable. The Arduino Nano, and Arduino-compatible Bare Bones Board and Arduino boards may provide male header pins on the underside of the board that can plug into solderless breadboards.

There are many Arduino-compatible and Arduino-derived boards. In which some are functionally equivalent to an Arduino and can be used vice versa. Many enhance the basic Arduino by adding output drivers, often used in school-level education to simplify the construction of buggies and small-scale robots. Others are electrically equivalent but change the form factor—sometimes retaining compatibility with shields, sometimes not. Some revision use completely different processors, with varying levels of similarity.

C. Software

The Arduino integrated development environment (IDE) is a cross-platform application written in Java and which is obtained from the IDE for the Processing programming language and the Wiring projects. It is sketched to introduce programming to artists and other newcomers unfamiliar with software development. It comprises a code editor with features such as syntax spotlighted, brace matching, and automated indentation and is also capable of compiling and uploading programs to the board with a single click. A program or codes written for Arduino is called a sketch [21].

The Arduino programs are written in C or C++. An Arduino IDE comes with a software library called "Wiring" from the original Wiring projects, which makes many common input/output operations much simple. Users only need to define two functions to make a runnable cyclic executive program:

- `setup()`: a function run one time at the start of a program that can initialize settings
- `loop()`: a function called repeatedly till the board powers off

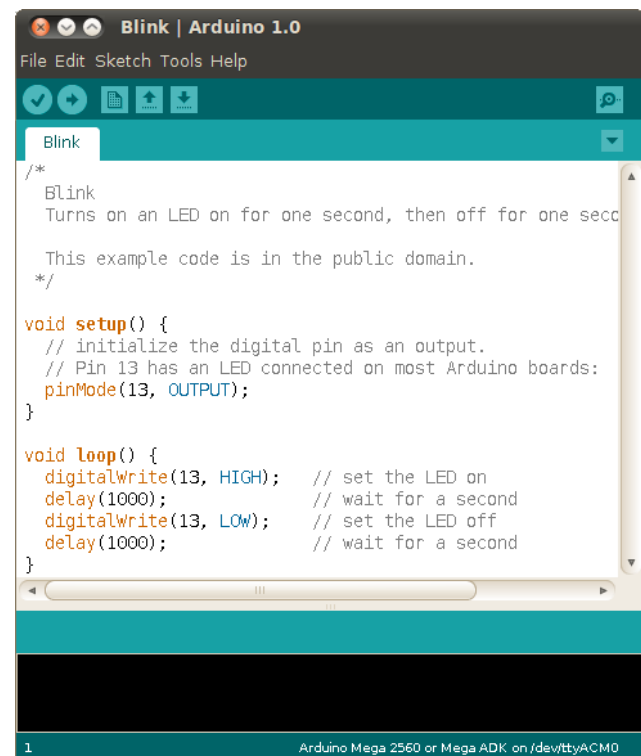


Fig. 6 Blink|Arduino 1.0

D. Arduino Software IDE





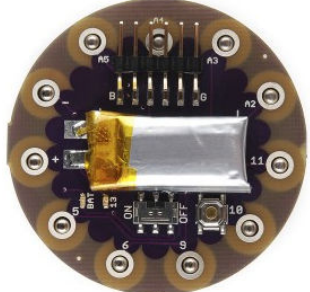

The Arduino IDE utilizes the GNU tool chain and AVR Libc to compile programs and uses avrdude to upload programs to the board.




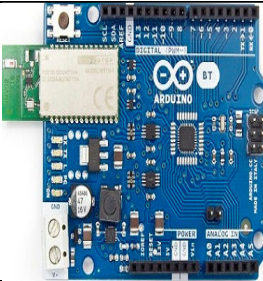
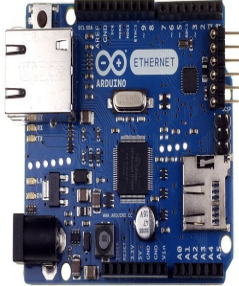
As the Arduino platform utilizes Atmel microcontrollers, Atmel's development environment, AVR Studio or the newer Atmel Studio, may also be used to develop software for the Arduino [26], [27].

E. Projects on Arduino

- LED Cube 8x8x8
- Power Laces- the Auto lacing shoe
- Plantduino Greenhouse
- The Eye Writer 2.0
- Twitter Mood Light - The World's Mood in a Box
- Flame throwing Jack-O'-Lantern
- Make a 24X6 LED matrix
- Secret Knock Detecting Door Lock
- Turn signal biking jacket
- Tree Climbing Robot

TABLE I
ARDUINO BOARD COMPARISON [8]

S.No	Name	Pictorial Representation	Processor	Features	Advantage	Limitation
01	ARDUINO UNO		ATmega328 (8-bit CPU, 16MHz clock speed, 2KB SRAM, 32KB flash storage)	14 digital I/O pins, 6 analog input pins, removable microcontroller	Microcontroller can be removed and replaced from the socket in case of breakdown	Doesn't have a lot of SRAM or flash memory that limits the kinds of programs you can load on the chip
02	ARDUINO LEONARDO		ATmega32u4 (8-bit CPU, 16MHz clock speed, 2.5KB SRAM, 32KB flash storage)	20 digital I/O pins, 12 of which is used as analog inputs, native USB support	ATmega32u4 has built-in USB communication (compatibility) eliminating the need for secondary processor. Leonardo to interface with PC, which sees it as a generic mouse or keyboard. It also has a few extra analog input pins.	Still has a few bugs that need ironing out and isn't quite as beginner friendly as the UNO
03	ARDUINO DUE		Atmel SAM3X8E ARM Cortex-M3 (32 bit CPU, 84MHz clock speed, 96KB SRAM, 512KB flash storage)	54 digital I/O pins, native USB port, 12 analog input pins, 2 analog output pins,	The Due is primarily for more complicated projects that can make use of its muscular processor, otherwise that needs more I/O pins than are found on the smaller Arduino boards.	It operates at 3.3 volts that limits the add-on hardware that's compatible with the Arduino Due-if an add-on board tries to send a 5 volt signal to the Due's I/O pins, it would damage the microcontroller.
04	ARDUINO MICRO		ATmega32u4 (8-bit CPU, 16MHz clock speed, 2.5KB SRAM, 32KB flash storage)	20 digital I/O pins, 12 of which is used as analog inputs, native USB support	Includes all of the power and functionality of a full-sized Arduino Leonardo board in a much smaller form factor. It is designed to easily slot into a breadboard, for faster prototyping.	Due to the small form factor, Arduino Micro will not work with many add-on boards.
05	LILYPAD ARDUINO		ATmega328 (8-bit CPU, 16MHz clock speed, 2KB SRAM, 32KB flash storage)	14 digital I/O pins, 6 analog input pins	Basically, designed for wearable's and e-textiles (fabric based projects)	Feature's the Leonardo's ATmega32u4 chip. But it has fewer I/O connections
06	ARDUINO ESPLORA		ATmega32u4 (8-bit CPU, 16MHz clock speed, 2.5KB SRAM, 32KB flash storage)	Lots of built-in input and output hardware	A whole bunch of I/O hardware soldered directly to the board. On input side you get a joystick, four buttons, a linear potentiometer (slider), a microphone, a light sensor, a temperature sensor and a three-axis accelerometer. For outputs, you get an RGB led, a buzzer and a TFT display connector to attach an LCD screen (not included).	The tradeoff is that you do not get the standard set of digital and analog I/O pins, which allows you to wire up all sorts hardware to your Arduino board.

S.No	Name	Pictorial Representation	Processor	Features	Advantage	Limitation
07	ARDUINO YUN		ATmega32u4 (8-bit CPU, 16MHz clock speed, 2.5KB SRAM, 32KB flash storage), Atheros AR9331 system on the chip	Wi-Fi enabled Linux based system on a chip, 14 digital, analog I/O pins, and 12 of which can be used as analog inputs. Native USB.	It is easier to connect to cloud-based services from the Arduino platform. It features a separate Linux-based system-on-a-chip on the motherboard.	The low-bandwidth, low-memory, microcontrollers have a hard time handling the verbose protocols used to access those services
08	ARDUINO ROBOT		2 x ATmega32u4 (8-bit CPU, 16MHz clock speed, 2.5KB SRAM, 32KB flash storage)	Wheels, 8 analogue input pins, 6 digital I/O pins, LCD screen	A little robot composed of two separate boards (a control board and a motor board) that each feature the Leonardo's ATmega32u4 processor. Though it's designed with room to add your own custom hardware	More expensive than other Arduino boards on account of having two separate boards
09	ARDUINO PRO MINI		ATmega168, Clock speed 8MHz(3.3v model) or 16MHz(5v model), SRAM-1 KB, Flash Memory-16 KB	Operating voltage-3.3V or 5V, Input Voltage-3.3V-12V, Digital I/O pins-14, Analog Input pins-8	Rather than requiring a physical press of the reset button before an upload, the Arduino Pro Mini is designed in a way that allows it to be reset by software running on a connected computer.	The Arduino pro mini is compact in size. Its size is about 1.3*0.70"
10	ARDUINO BT (Blue Tooth)		ATmega328, Clock speed 16MHz, SRAM-2KB, Flash Memory-32KB, EEPROM-1 KB	Operating voltage-5V, Input Voltage-2.5V-12V, Digital I/O pins-14, Analog Input pins-6, D/C current per 3.3V pins-500 mA, D/C current per 5V pins-1000 mA	The board replaces the USB plug with a Bluetooth module	Higher voltages or reversed polarity in the power supply can damage or destroy the board. The protection for reverse polarity connection is ONLY on the screw terminal.
13	ARDUINO ETHERNET		ATmega328, Clock speed 16MHz, SRAM-2KB, Flash Memory-32KB, EEPROM-1 KB	Operating voltage-5V, Input Voltage plug-6V-20V, Input Voltage PoE-36V-57V, Digital I/O pins-14, Analog Input pins-6, D/C current per 3.3V pins-50 mA	It features support for automatic reset, allowing sketches to be uploaded without pressing the reset button on the board. When plugged into a USB to Serial adapter, the Arduino Ethernet is powered from the adapter.	In order to use Ethernet, pins 10 to 13 should be reserved

From this list of Arduino boards, we are choosing Arduino UNO R3 for our survey paper.

E. Arduino Uno

The Arduino Uno is a microcontroller board based on the ATmega328 (datasheet). It contains 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, USB connection, power jack, 16 MHz ceramic resonator, an ICSP header, and a reset button. It contains everything which is needed to support the microcontroller; simply connect it to a computer with a USB cable or power it with an AC-to-DC adapter or battery to get started.

The Uno differs from all preceding boards in that it does not use the FTDI USB-to-serial driver chip. Instead, it features the

Atmega16U2 (Atmega8U2 up to version R2) programmed as a USB-to-serial converter.

Revision 2 of the Arduino Uno board has a resistor pulling 8U2 HWB line to ground, making it easier to put into DFU mode.

Revision 3 of the Arduino Uno board has the following new features:

1.0 pinout: added SDA and SCL pins that are nearer to the AREF pin and two other new pins placed near to the RESET pin, IOREF that allows the shields to adapt to the voltage provided from the board. In future, shields would be compatible with both the board that uses AVR, which operates with 5V and Arduino Due which operates by 3.3V. The second one is not a connected pin that is reserved for future purposes.

- Stronger RESET circuit.
- Atmega 16U2 replace the 8U2.
- Processor: ATmega328 (8-bit CPU, 16MHz clock speed, 32KB flash storage, 2KB SRAM)
- Features: 6 analog input pins, 14 digital I/O pins, removable microcontroller
- Form Factor: 2.7" * 2.1" rectangle
- Price: \$30 [7].

The Arduino Uno is the most "standard" Arduino board currently in the market, and is probably the best choice for beginners just getting started with the platform. The board is well-suited with more shields (add-on boards) than other models.

Arduino simplifies the process of working with microcontrollers, and offers some advantages for students, teachers and interested amateurs over other systems:

- Cross-platform - The Arduino software runs on Macintosh OSX, Windows and Linux operating systems. Most of the microcontroller systems are limited to Windows.
- Simple, clear programming environment - The Arduino programming environment is easy-to-use for the beginners, yet flexible enough for the advanced users. For teachers, it is conveniently based on the Processing programming environment, hence students are learning to program in that environment will be familiar with the look and feel of Arduino
- Open source and extensible software - The Arduino software is published as open source tools, available for extension by the experienced programmers. The language can be expanded through the C++ libraries, and people wanting to understand the technical details can make the leap from Arduino to the AVR C programming language on which it is based. Likewise, you have the capacity to add AVR-C code directly into your Arduino programs if you want to.
- Open source and extensible hardware - The Arduino is based on Atmel's ATMEGA8 and ATMEGA168 microcontrollers. The plans for modules are published under a Creative Commons license, hence experienced circuit designers can create their own version of the module, which can be extended and improved. Even relatively inexperienced users can build the breadboard version of the module in order to understand how it works and save money.

The Uno's main limitation is ATmega328 chip, which doesn't have lot of SRAM or flash memory, which limits the kinds of programs you can load on the chip—if your project involves a display or otherwise needs to store and use any form of images or audio data, 2KB of memory isn't going to be enough [7].

Features of ATmega328P Microcontroller (used by the Arduino):

- AVR 8-bit RISC architecture
- Available in DIP package
- Up to 20 MHz clock
- 32kB flash memory
- 1 kB SRAM

- 23 programmable I/O channels
- Six 10-bit ADC inputs
- Three timers/counters
- Six PWM outputs [16].

Bare Minimum:

The bare minimum of code is needed to start an Arduino sketch.

Hardware Required:

- Arduino Board

Code:

```
void setup () {
// put your setup code here, to run once:
}
void loop () {
// put your main code here, to run repeatedly:
} [10].
```

Blink:

Turn an LED on and off.

Hardware Required:

- Arduino Board
- LED
- Resistor, anything between 220 ohm to 1K ohm

Code:

```
/*
Turns on LED on for one second, then off for one second,
repeatedly.
*/
// Pin 13 has a LED connected on most of the Arduino boards.
// give it a name:
int led = 13;
// the setup routine runs once when you press the reset:
void setup () {
// initialize the digital pin as a output.
pinMode (led, OUTPUT);
}
void loop ()
{
digitalWrite (led, HIGH); // turn the LED on (HIGH is the
voltage level)
delay (1000); // wait for a second
digitalWrite(led, LOW); // turn the LED off by making the
voltage LOW
delay (1000); // wait for a second
} [11].
```

Digital Read Serial:

It reads the switch, print the state out to the Arduino Serial Monitor.

Hardware Required

- Arduino Board
- A momentary switch, button, or toggle switch
- 10k ohm resistor
- breadboard
- hook-up wire

Code:

```

/*
DigitalReadSerial
Reads a digital input on pin 2, prints the result to the serial monitor
*/
// digital pin 2 has a pushbutton attached towards it. Give it a
name:
int pushButton = 2;
// the setup routine runs once when you press the reset:
void setup ()
{
// initialize serial communication by 9600 bits per second:
Serial.begin(9600);
// make the pushbutton's pin an input:
pinMode(pushButton, INPUT);
}
void loop ()
{
// read the input pin:
int buttonState = digitalRead(pushButton);
// print out the state of the button:
Serial.println(buttonState);
delay (1);
// delay in between reads for stability
} [12].

```

Analog Read Serial:

It reads the potentiometer, print its state out to the Arduino Serial Monitor.

Hardware Required:

- Arduino Board
- 10-kilohm Potentiometer

Code:

```

/*
AnalogReadSerial
Reads the analog input on pin 0, prints the result to the serial
monitor.
Attach the center pin of the potentiometer to pin A0, and the
outside pins to +5V and ground.
*/
// the setup routine runs once when you press the reset:
void setup ()
{
// initialize serial communication by 9600 bits per second:
Serial.begin(9600);
}

void loop ()
{
// read the input on analog pin 0:
int sensorValue = analogRead(A0);
// print out the value you read:
Serial.println(sensorValue);
delay (1);
// delay in between reads for stability
} [9].

```

Fade:

Following code demonstrates the process of analog signals output to fade an LED.

Hardware Required

- Arduino board
- Breadboard
- a LED
- a 220 ohm resistor

Code:

```

/*
Fade
This example shows how to fade an LED on pin 9
using the analogWrite() function.
*/
int led = 9; // the pin that the LED is attached to
int brightness = 0; // how bright the LED is
int fadeAmount = 5; // how many points to fade the LED by
// the setup routine runs once when you press reset:
void setup ()
{
// declare pin 9 to be an output:
pinMode (led, OUTPUT);
}
// the loop routine runs over and over again forever:
void loop ()
{
// set the brightness of pin 9:
analogWrite (led, brightness);
// change the brightness for next time through the loop:
brightness = brightness + fadeAmount;
// reverse the direction of the fading at the ends of the fade:
if (brightness == 0 || brightness == 255)
{
fadeAmount = -fadeAmount ;
}
// wait for 30 milliseconds to see the dimming effect
delay (30);
} [13].

```

Read Analog Voltage:

It reads an analog input and prints the voltage to the serial monitor.

Hardware Required

- Arduino Board
- a variable resistor, like a potentiometer

Code:

```

/*
ReadAnalogVoltage
Reads an analog input on pin 0, converts it to voltage, and prints
the result to the serial monitor.
Attach the center pin of a potentiometer to pin A0, and the outside
pins to +5V and ground.
*/
// the setup routine runs once when you press reset:
void setup ()
{
// initialize serial communication at 9600 bits per second:
Serial.begin(9600);
}
// the loop routine runs over and over again forever:
void loop ()
{

```

```
// read the input on analog pin 0:
int sensorValue = analogRead(A0);
// Convert the analog reading (which goes from 0 - 1023) to a
voltage (0 - 5V):
float voltage = sensorValue * (5.0 / 1023.0);
// print out the value you read:
Serial.println(voltage);} [14].
```

IV. CONCLUSION

In this paper we have reviewed various types of controllers. The advantages of using different Arduino board are: Arduino Uno-easily replaceable, Arduino Leonardo-eliminates the need of secondary processor and Arduino Due-used in complicated project. Arduino micro –enables faster prototyping, Lily pad Arduino – wearable's and e-textiles, Arduino Esplora- has joysticks, microphone, sensors on input side and buzzer on output side, Arduino Yun-support cloud based services, Arduino Robot-support our own customized hardware parts. This study provides a wide description about Arduino processor; it will be helpful for many robotic researchers.

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